
Elliptic PDE learning is provably data-efficient

Nicolas Boullé



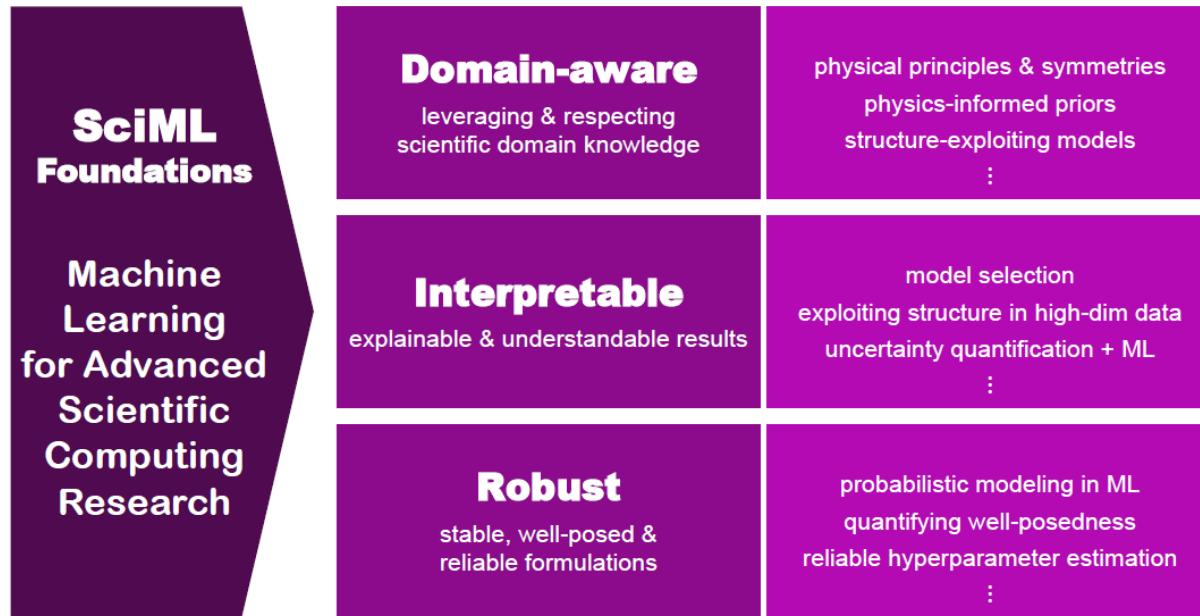
Diana Halikias



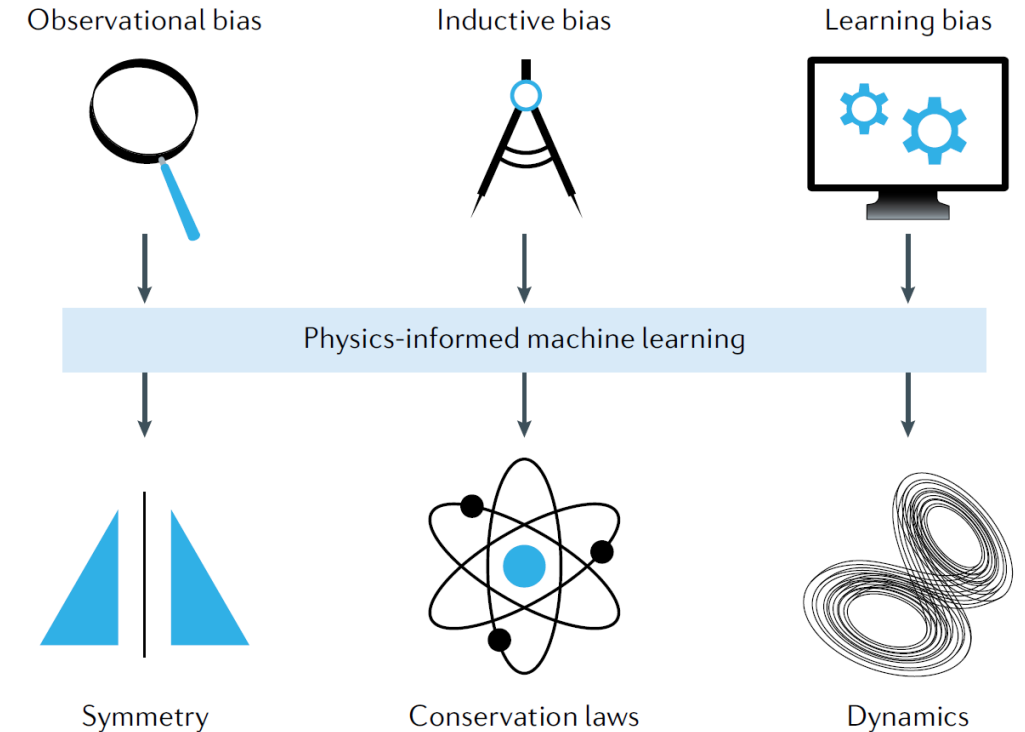
Alex Townsend



Scientific machine learning



[Baker et al., DOE Tech. Report, 2019]

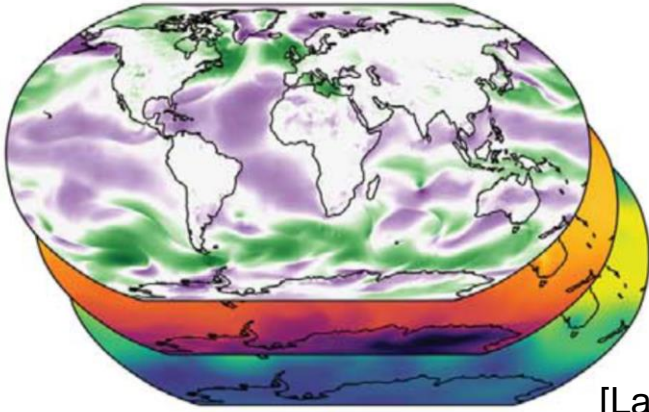


[Karniadakis et al., 2021]

Combining numerical analysis and machine learning for scientific discoveries.

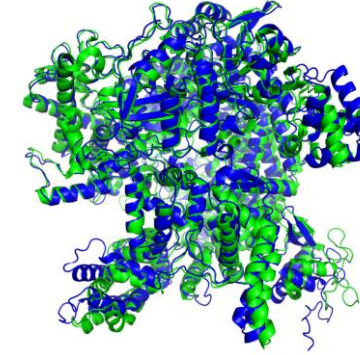
Recent applications of SciML

Weather forecasting



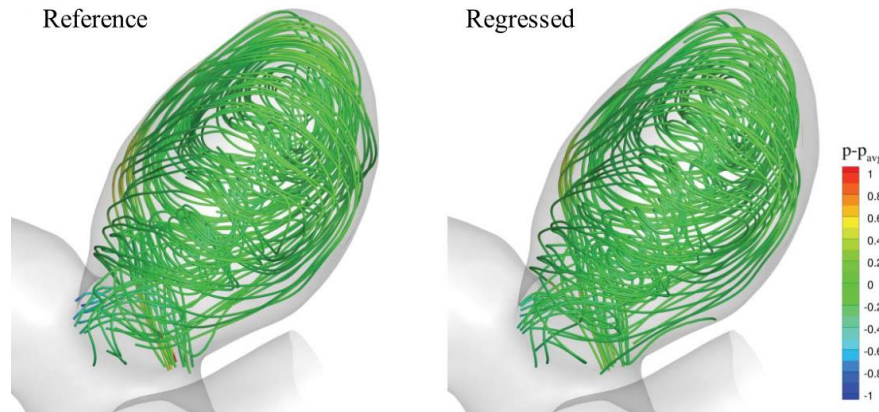
[Lam et al., Science, 2023]

Protein folding



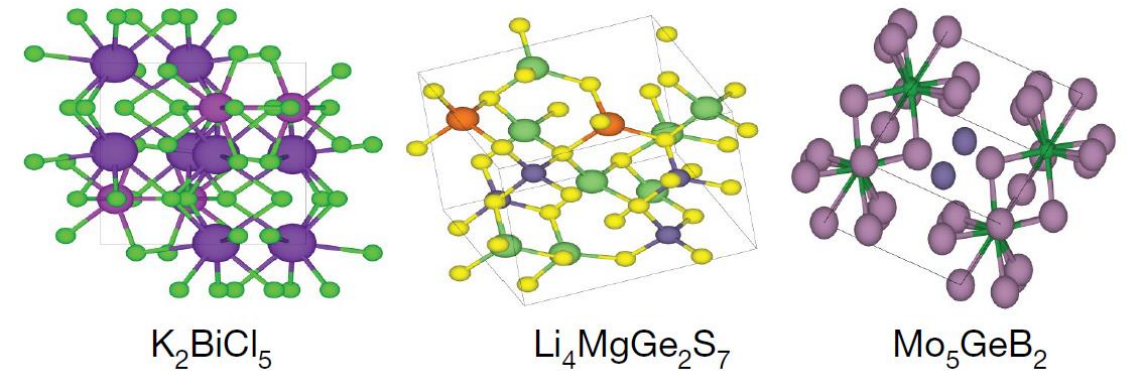
[Jumper et al., Nature, 2021]

Numerical simulations



[Raissi, Yazdani, Karniadakis, Science, 2020]

Materials discovery



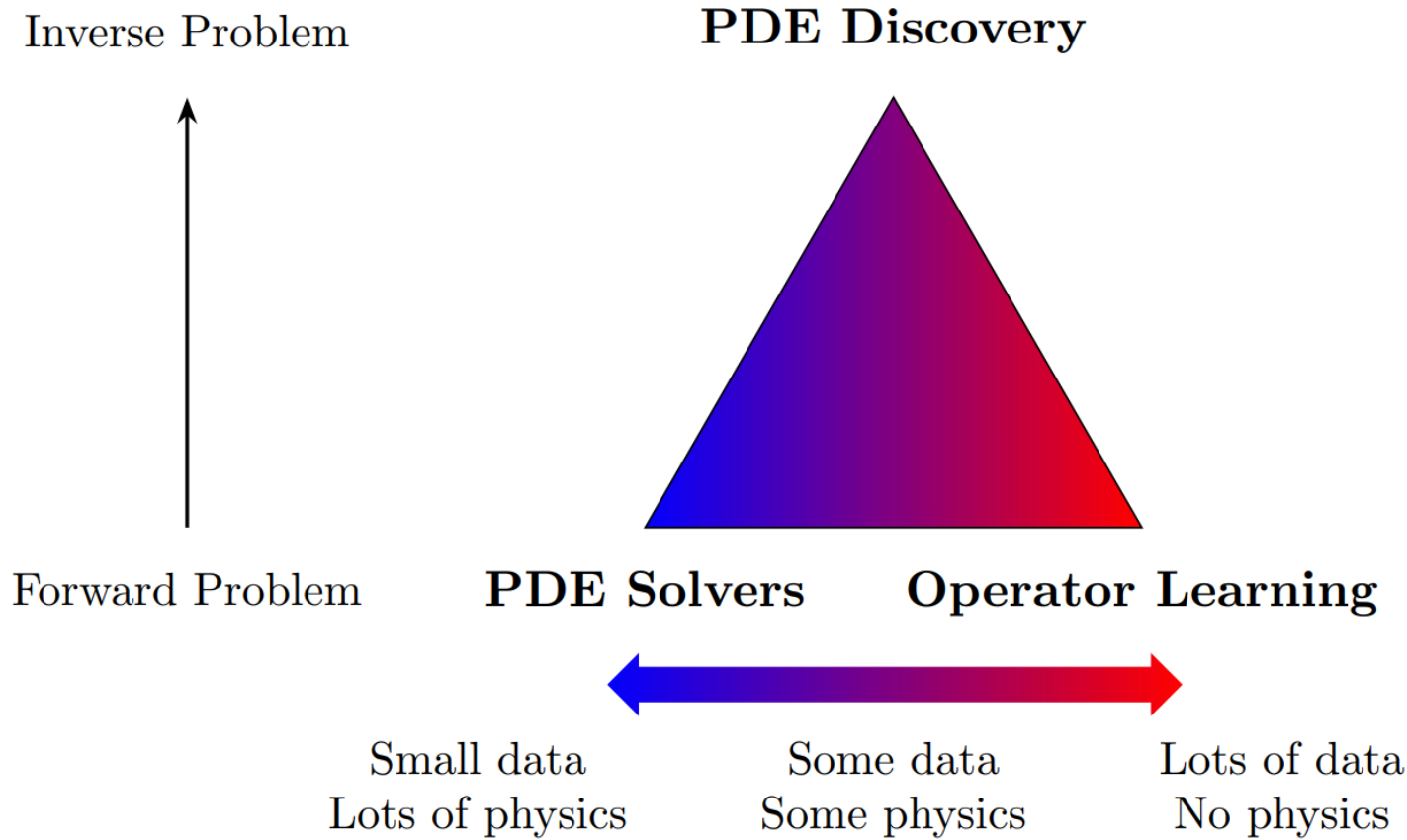
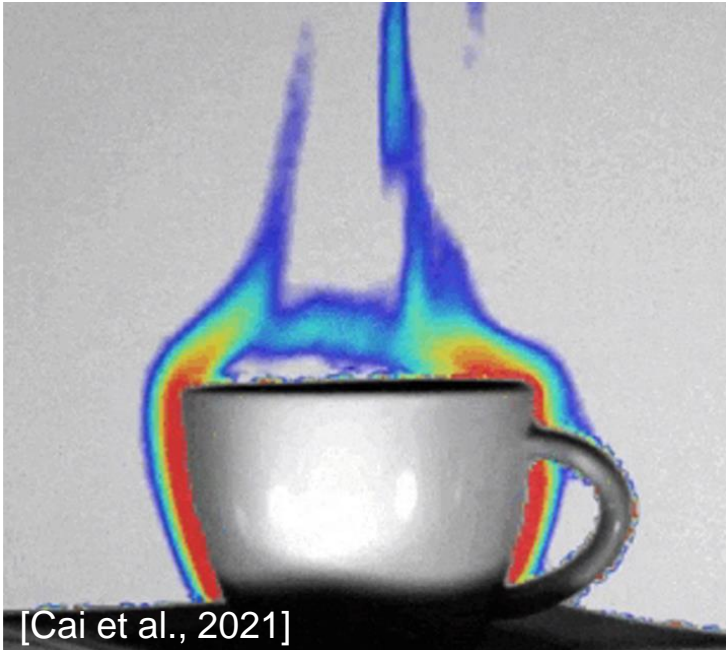
[Merchant et al., Nature, 2023]

Operator learning

Physics-informed machine learning

George Em Karniadakis^{1,2}, Ioannis G. Kevrekidis^{3,4}, Lu Lu⁵, Paris Perdikaris⁶, Sifan Wang⁷ and Liu Yang¹

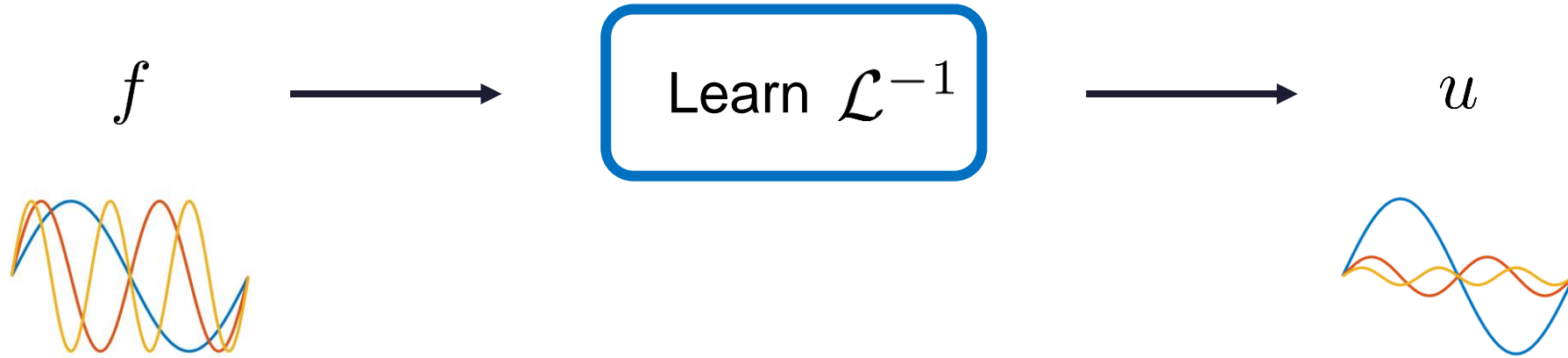
Abstract | Despite great progress in simulating multiphysics problems using the numerical discretization of partial differential equations (PDEs), one still cannot seamlessly incorporate noisy data into existing algorithms, mesh generation remains complex, and high-dimensional problems governed by parameterized PDEs cannot be tackled. Moreover, solving inverse problems with hidden physics is often prohibitively expensive and requires different formulations and elaborate computer codes. Machine learning has emerged as a promising alternative, but training deep neural networks requires big data, not always available for scientific problems. Instead, such networks can be trained from additional information obtained by enforcing the physical laws (for example, at random points in the continuous space-time domain). Such physics-informed learning integrates (noisy) data and mathematical models, and implements them through neural networks or other kernel-based regression networks. Moreover, it may be possible to design specialized network architectures that automatically satisfy some of the physical invariants for better accuracy, faster training and improved generalization. Here, we review some of the prevailing trends in embedding physics into machine learning, present some of the current capabilities and limitations and discuss diverse applications of physics-informed learning both for forward and inverse problems, including discovering hidden physics and tackling high-dimensional problems.



Recent survey: B., Townsend, “A Mathematical Guide to Operator Learning”, 2023.

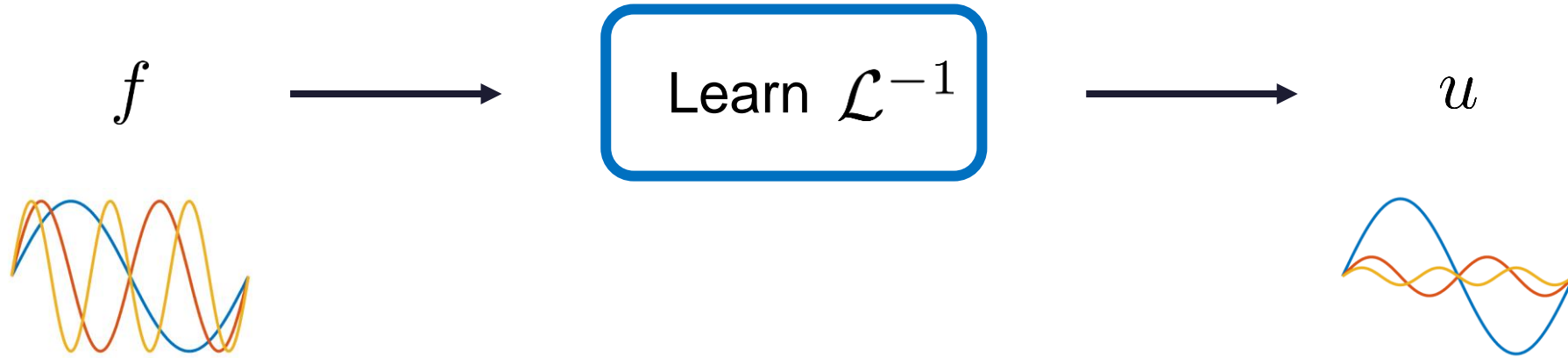
Introduction

Aim: Learn the **solution operator** of unknown linear PDEs $\mathcal{L}(u) = f$ from observation data:



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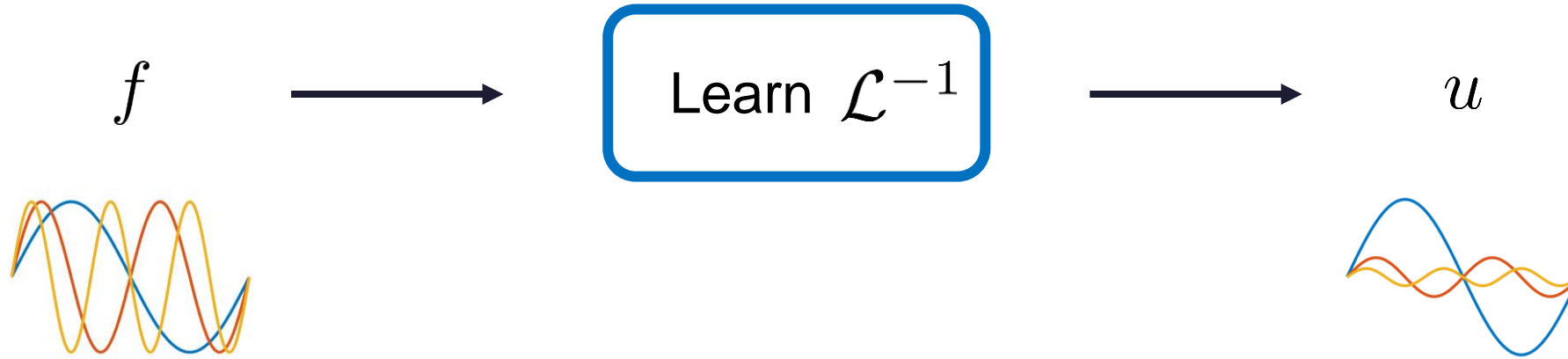


Main contributions:

- Theoretical result quantifying the **number of training pairs** (f, u) needed
- A practical deep learning approach to learn **Green's functions**

Introduction

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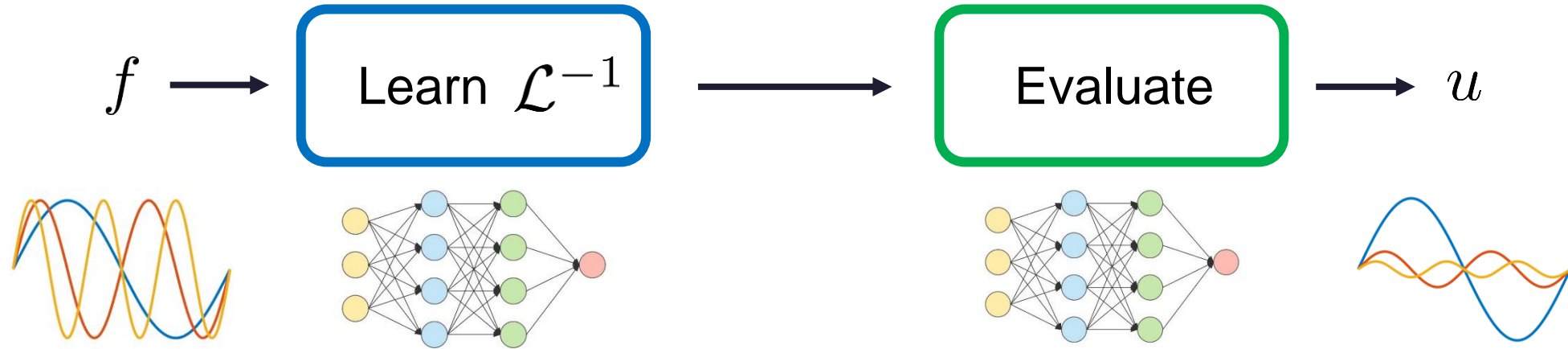


Key ideas:

- Randomized numerical linear algebra
- Rational neural networks
- Regularity of Green's functions

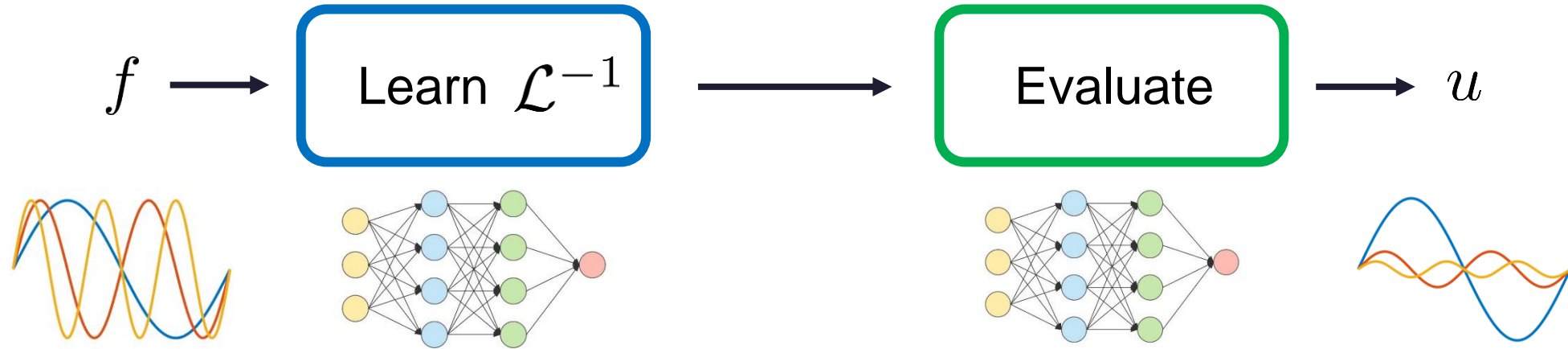
Standard approaches of PDE learning

Approximating the solution operator $\mathcal{L}^{-1}(f) = u$

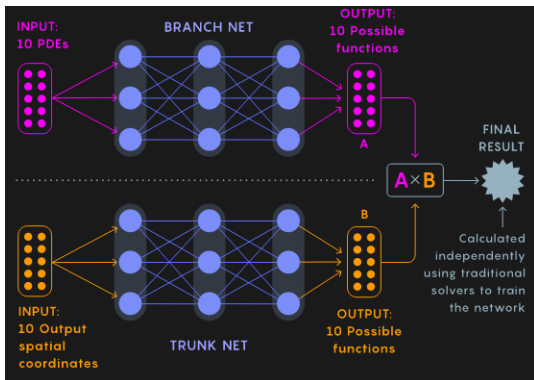


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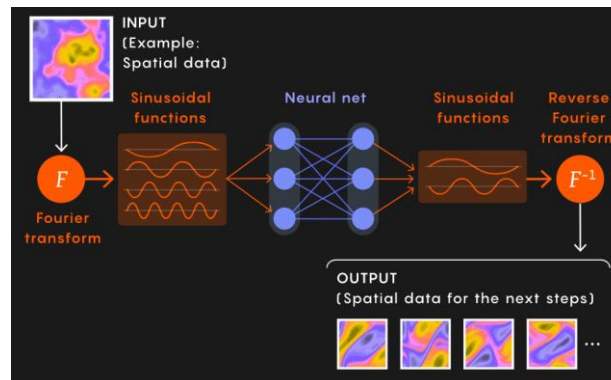


DeepONet



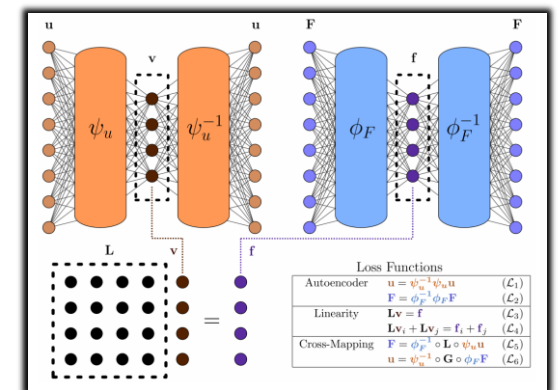
[Quanta Magazine; Lu et al, 2021]

Fourier Neural Operator



[Quanta Magazine; Li et al, 2020]

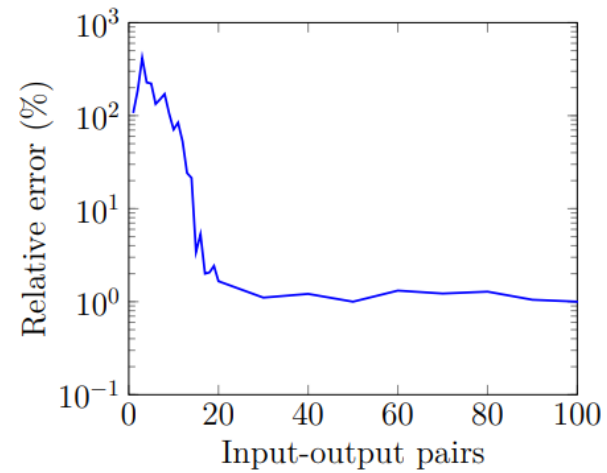
DeepGreen



[Gin et al., 2020]

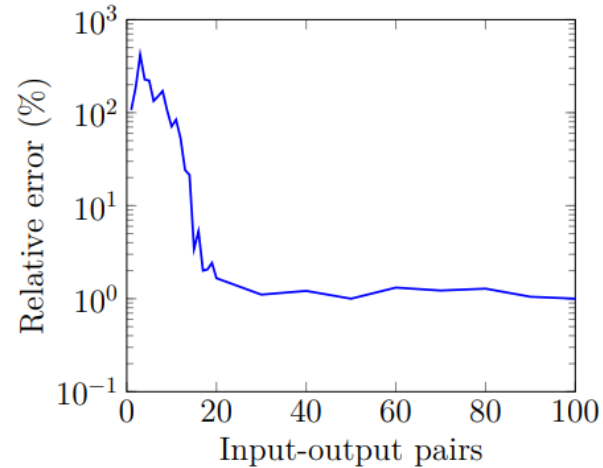
Main challenges of PDE learning

1. Theoretical results



Main challenges of PDE learning

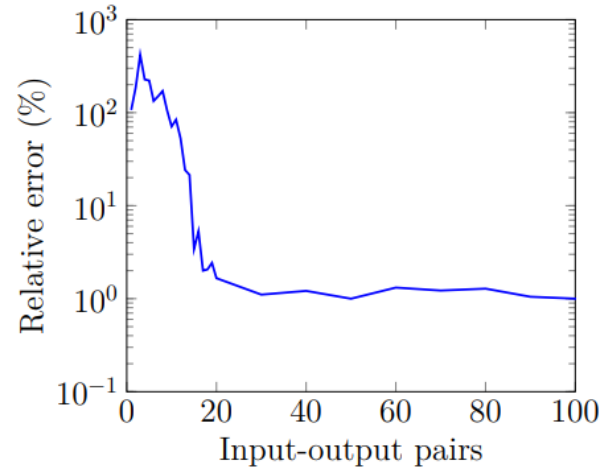
1. Theoretical results



- Type and number of training data
- Performance guarantees
- Neural network architectures
- Noise robustness

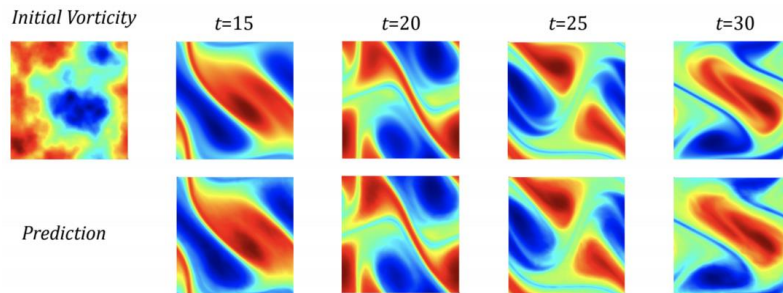
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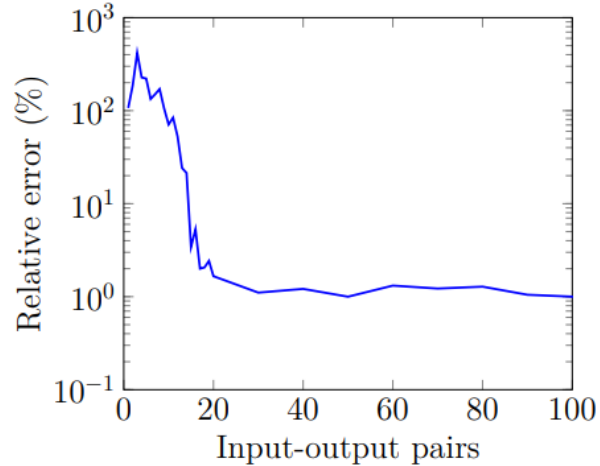
2. Interpretability of the model



[Li et al, 2020]

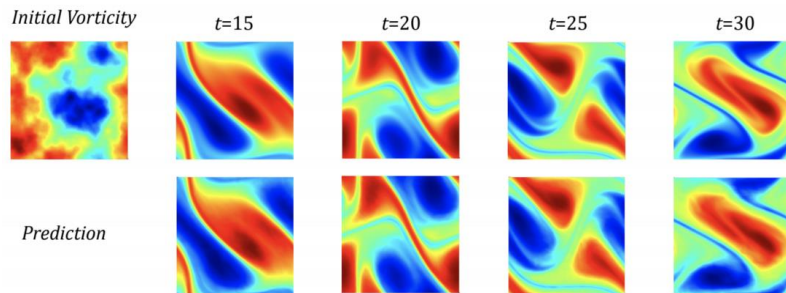
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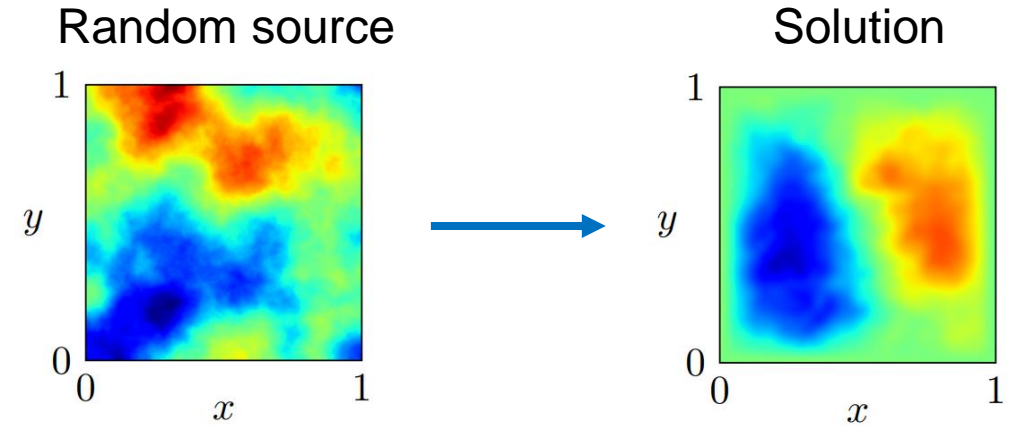
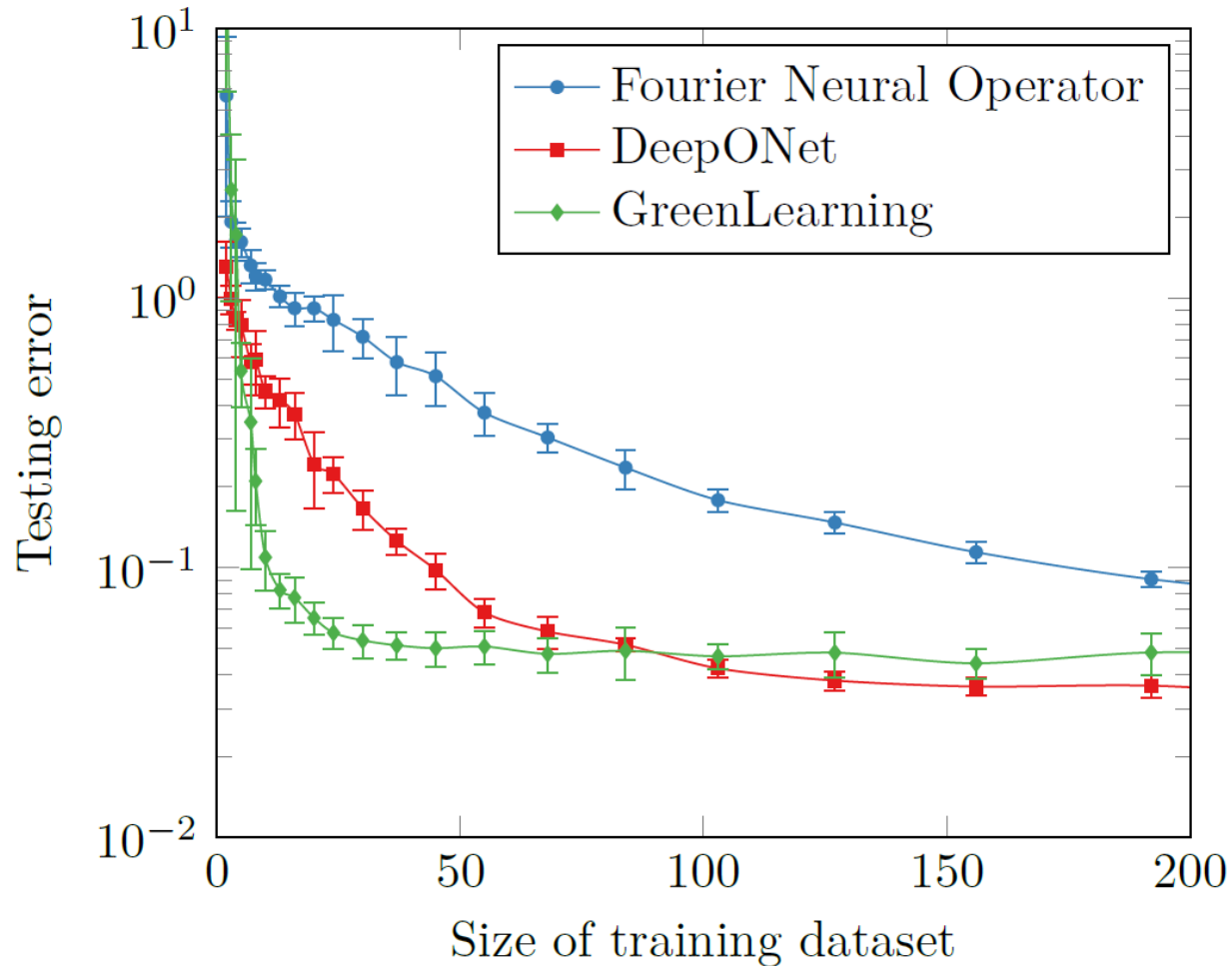


[Li et al, 2020]

- Dominant modes
- Symmetries
- Conservation laws
- Singularities

PDE learning is data-efficient

Learn the solution operator of Poisson equation



How much training data is needed to learn a PDE?

Related works: [B., Townsend, 2022], [B. et al., 2022], [Chen et al., 2023], [de Hoop et al., 2021], [Lu et al., 2021], [Schäfer, Owhadi, 2021], [Schäfer et al., 2017]

Green's functions

Linear differential equation:

$$\begin{array}{l} \mathcal{L}u = f \\ u|_{\partial D} = 0 \end{array} \longrightarrow u(x) = \int_D G(x, y) f(y) \, dy$$



George Green

Green's functions

Linear differential equation:

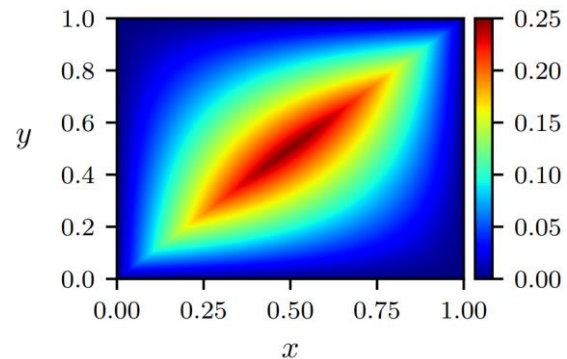
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Poisson equation

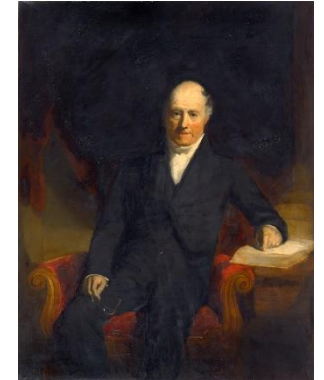
$$\begin{array}{l} -\nabla^2 u = f \\ u(0) = u(1) = 0 \end{array}$$



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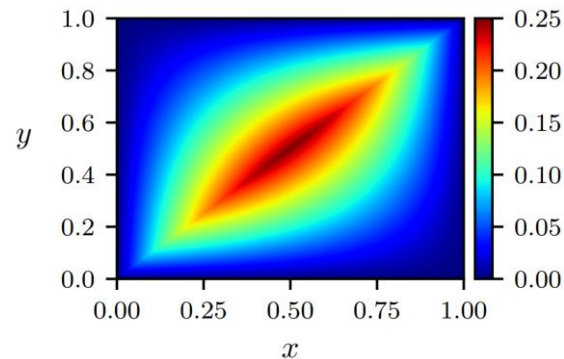
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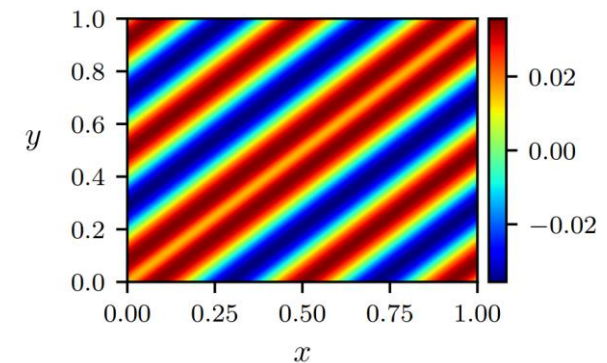
Poisson equation

$$\begin{array}{l} -\nabla^2 u = f \\ u(0) = u(1) = 0 \end{array}$$



Helmholtz equation

$$\begin{array}{l} \nabla^2 u + k^2 u = f \\ u(0) = u(1) \end{array}$$



Learning Green's functions of elliptic PDEs

Elliptic PDEs in 3D of the form:

$$\mathcal{L}u := -\nabla \cdot (A(x)\nabla u) = f \quad \longrightarrow \quad u(x) = \int_D G(x, y) f(y) \, dy$$

Theorem (B., Halikias, Townsend, 2023).

*There is a randomized algorithm that achieves **exponential convergence** for learning the Green's function, with exceptionally high probability of success.*

The proof combines core techniques in numerical analysis and generalizes them to **infinite dimensions**: randomized SVD + hierarchical matrices + peeling.

Randomized numerical linear algebra

Randomized singular value decomposition

Best rank k approximation

$$A = \begin{matrix} \boxed{U} & \boxed{\Sigma} & \boxed{V^*} \end{matrix}$$

$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_k \geq \dots$

Eckart-Young theorem



$$\epsilon_k = \sqrt{\sum_{j=k+1}^n \sigma_j(A)^2}$$

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Theorem (Halko, Martinsson, Tropp, 2011).

We can construct an approximation A_k of A from $k+5$ *random* input vectors such that

$$\mathbb{P} \left[\|A - A_k\|_F \leq (1 + 15\sqrt{k+5})\epsilon_k \right] \geq 0.999$$

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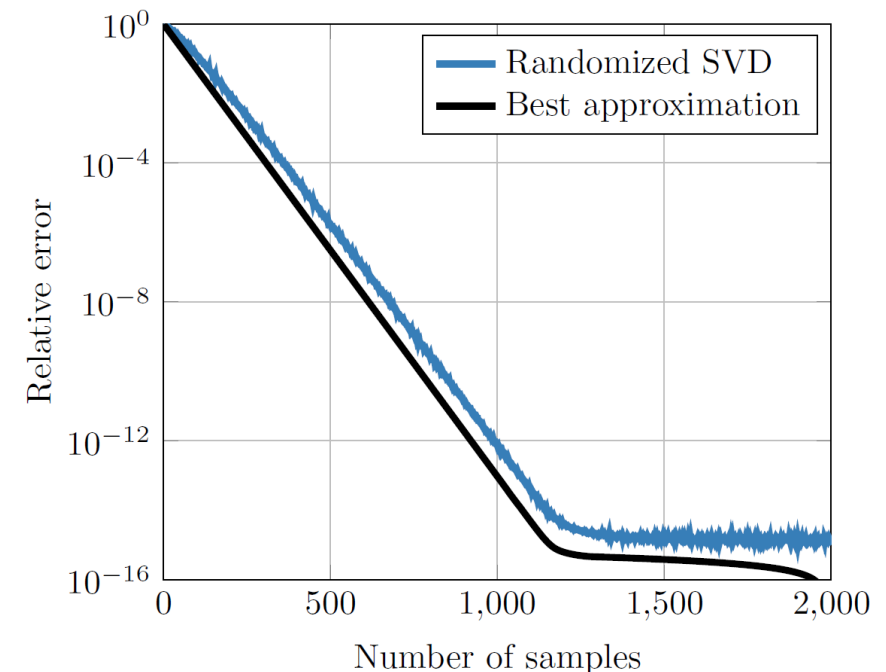
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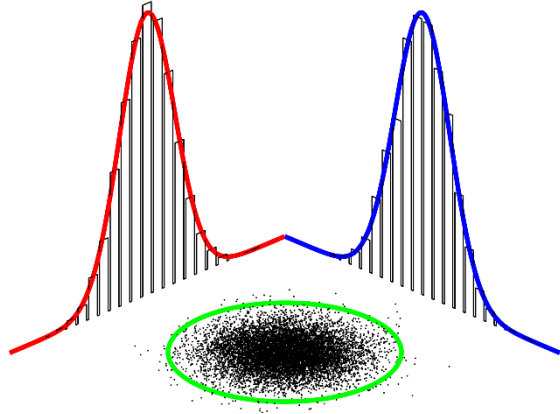
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Generalization of the randomized SVD

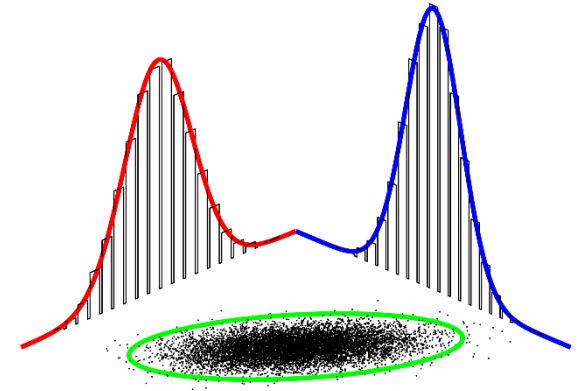
Standard Gaussian vectors



[B., Townsend, 2022]

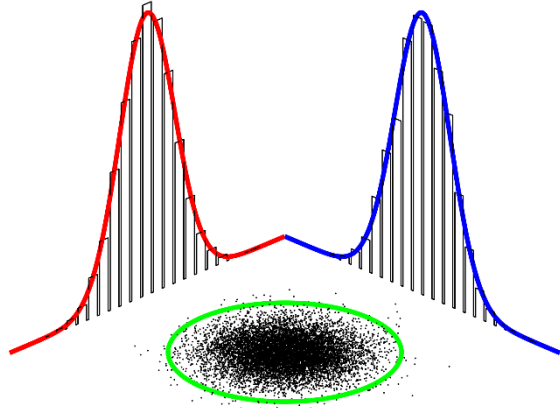


Correlated Gaussian vectors



Generalization of the randomized SVD

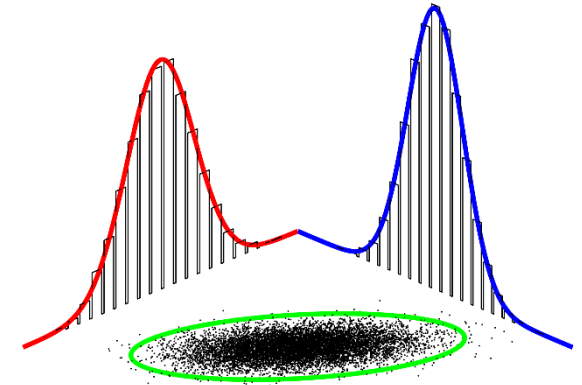
Standard Gaussian vectors



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Correlated Gaussian vectors



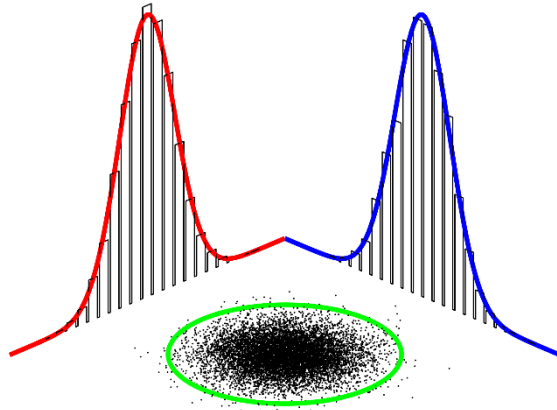
Theorem (B., Townsend, 2022).

We can construct an approximation A_k of A from $k+5$ *correlated random* input vectors such that

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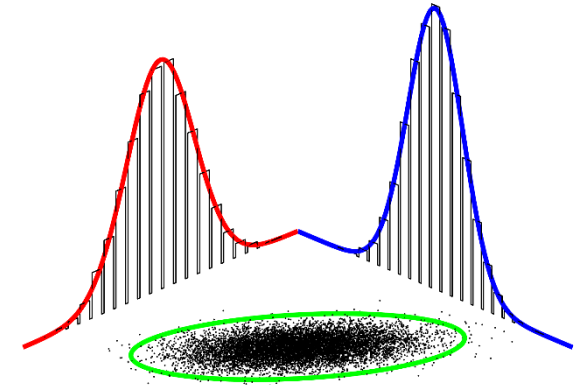
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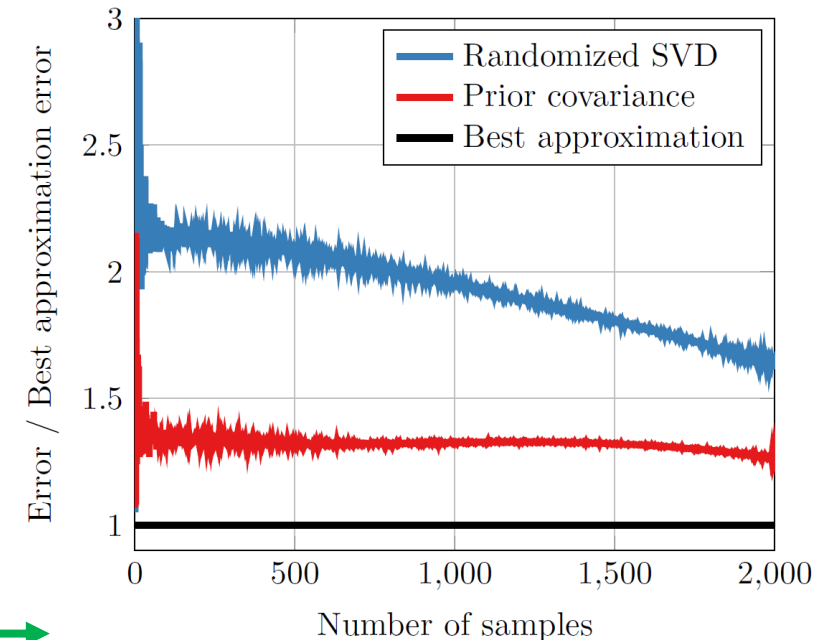


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Prior knowledge on A



Hilbert-Schmidt operators

Definition:

Bounded linear operator \mathcal{F} between Banach spaces with finite HS norm.



David Hilbert



Erhard Schmidt

Hilbert-Schmidt operators

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Matrices

$$\left[\begin{array}{c} A \end{array} \right] \quad \begin{aligned} \|A\|_{\text{HS}} &= \|A\|_{\text{F}} \\ &= \sqrt{\text{Tr}(A^* A)} \end{aligned}$$

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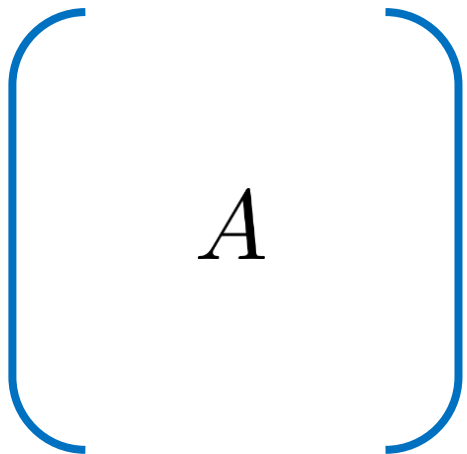


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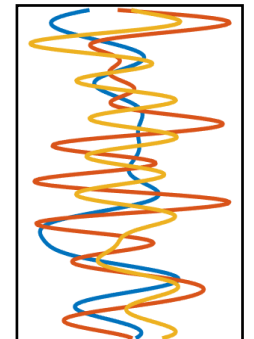
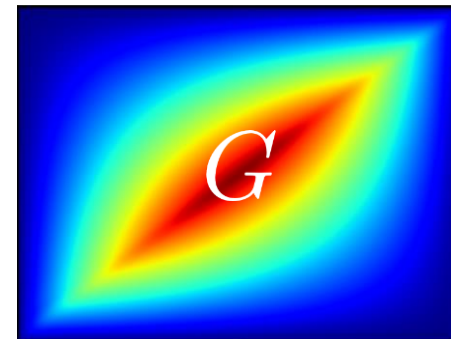
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Integral operators

$$\mathcal{F}(f)(x) = \int_D G(x, y) f(y) \, dy$$



Properties of Hilbert-Schmidt operators

Norm

$$\|\mathcal{F}\|_{\text{HS}} = \|G\|_{L^2(D \times D)}$$

Properties of Hilbert-Schmidt operators

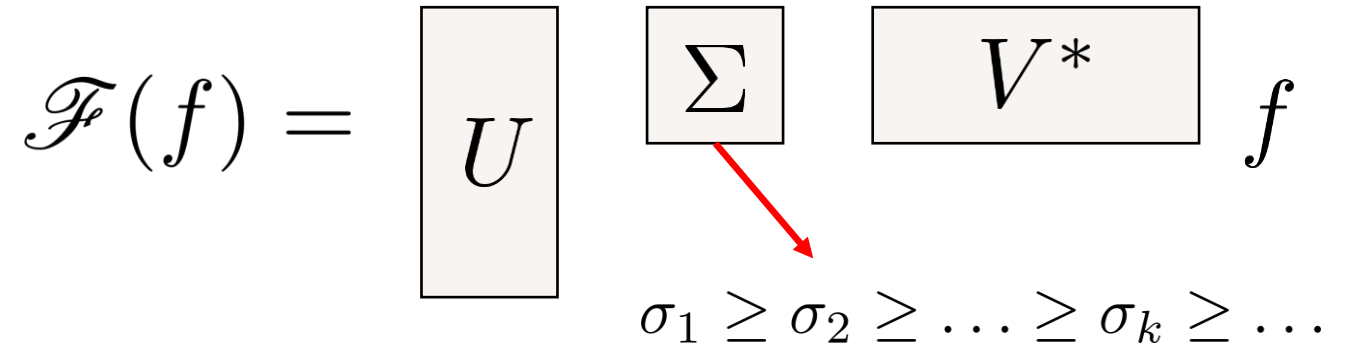
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Eckart-Young-Mirsky theorem

Truncating the SVD gives the best rank k approximation in the HS norm:

$$\epsilon_k = \|\mathcal{F} - \mathcal{F}_k\|_{\text{HS}} = \sqrt{\sum_{j=k+1}^{\infty} \sigma_j^2}$$



Carl Eckart



Leon Mirsky

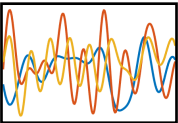
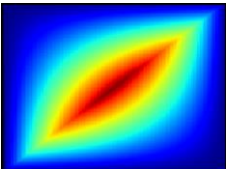
Randomized SVD for HS operators

$$A \times F$$

A	0.7 0.1
	-0.4 0.2
	0.8 0.5

[B., Townsend, 2022]



$$\int_D G(x, y) f(y) dy$$


Randomized SVD for HS operators

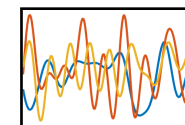
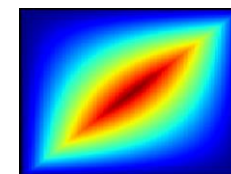
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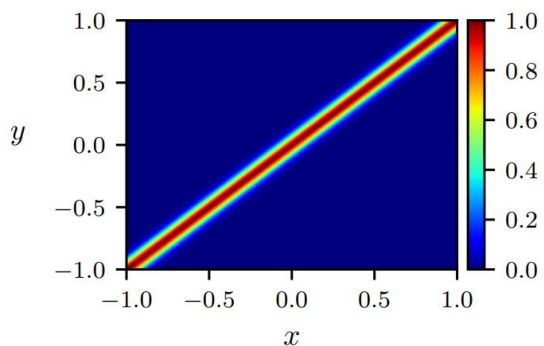
[B., Townsend, 2022]



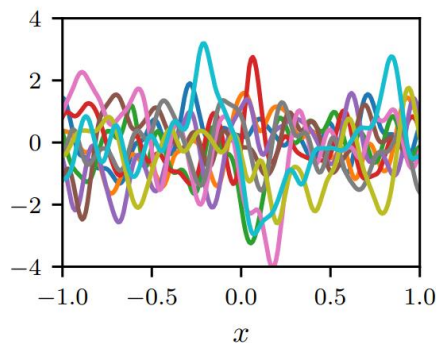
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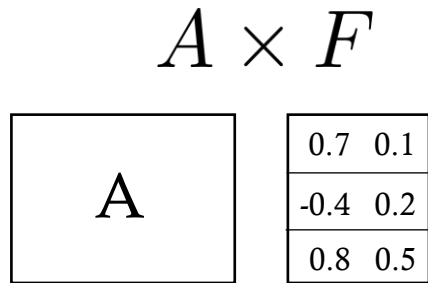
Covariance
kernel



Random
functions



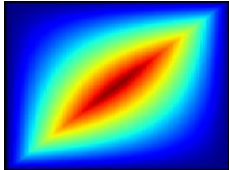
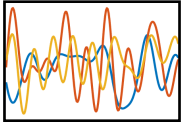
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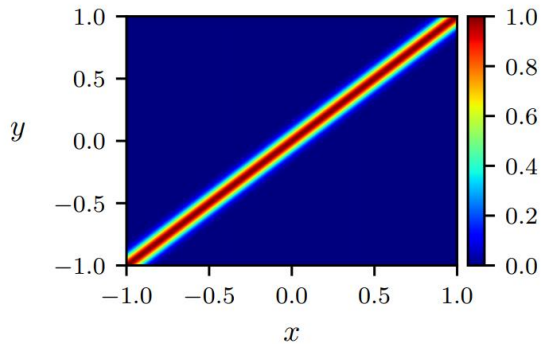
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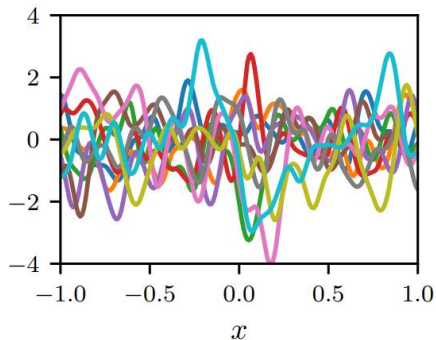
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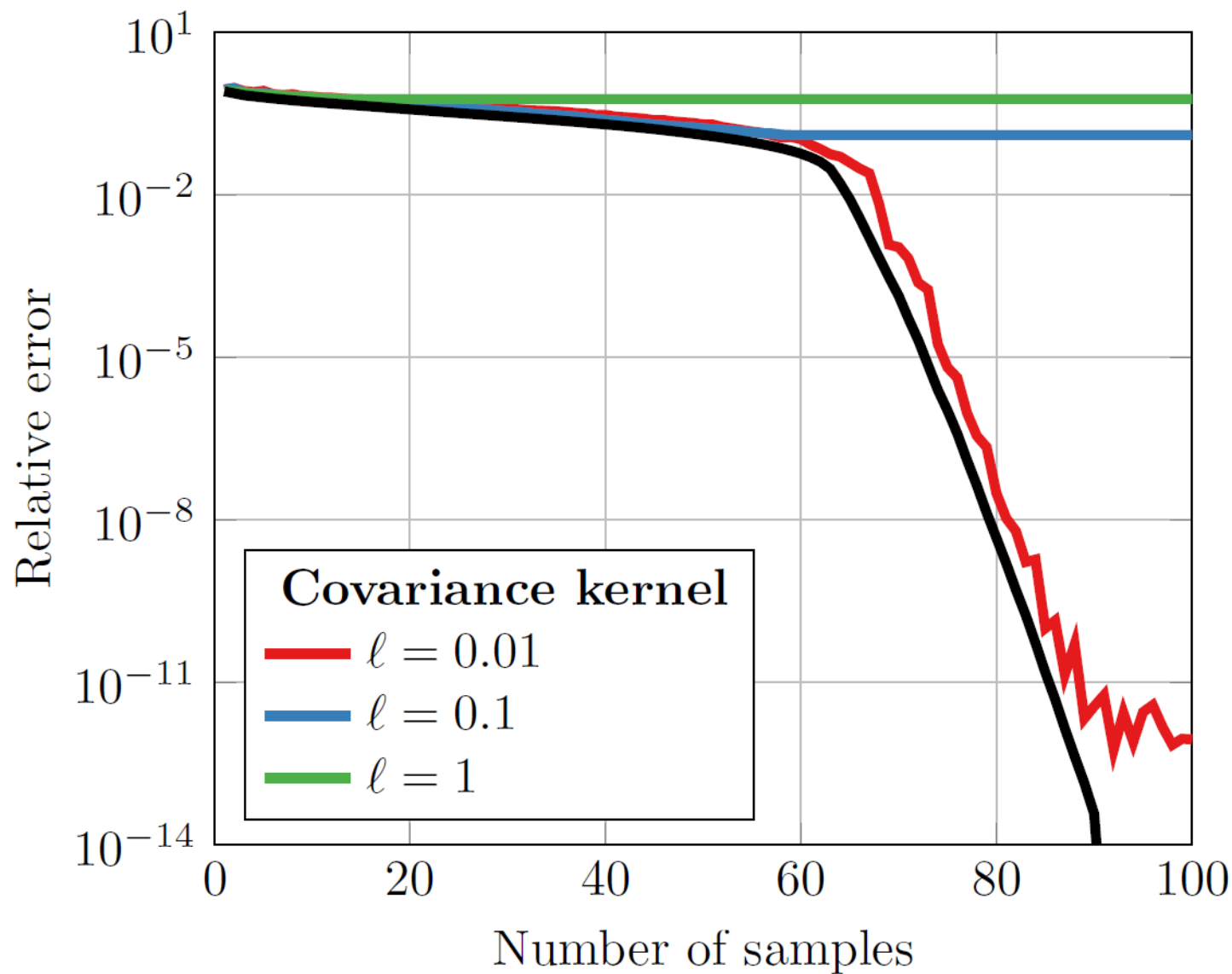
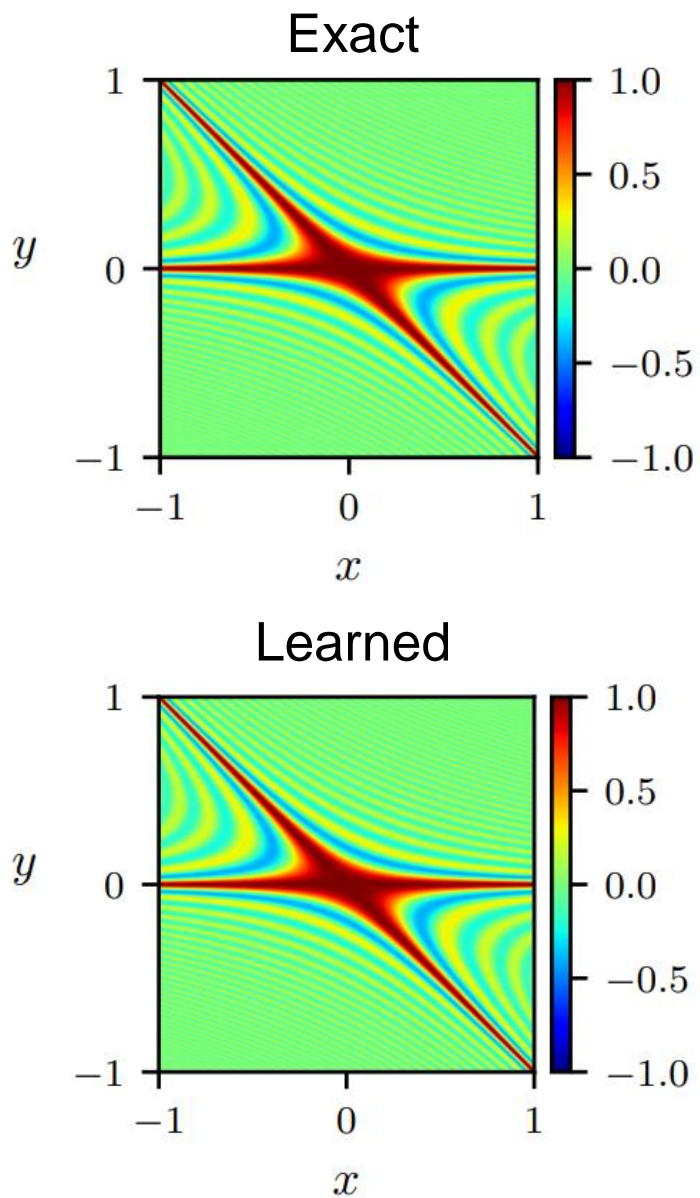


Theorem (B., Townsend, 2022).

We can construct an approximation G_k of G from $k+5$ *random input functions* f such that

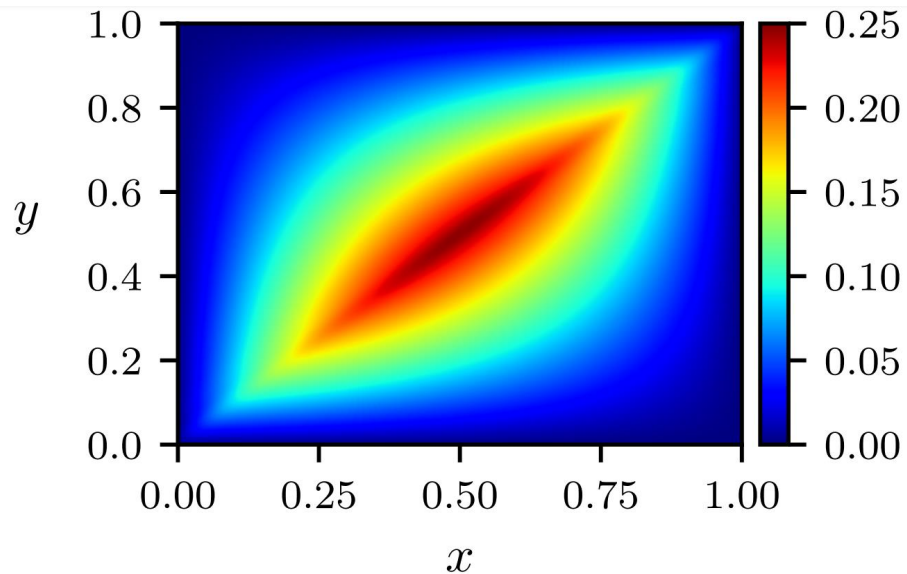
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Randomized SVD for HS operators



Randomized SVD for Green's functions

Green's function



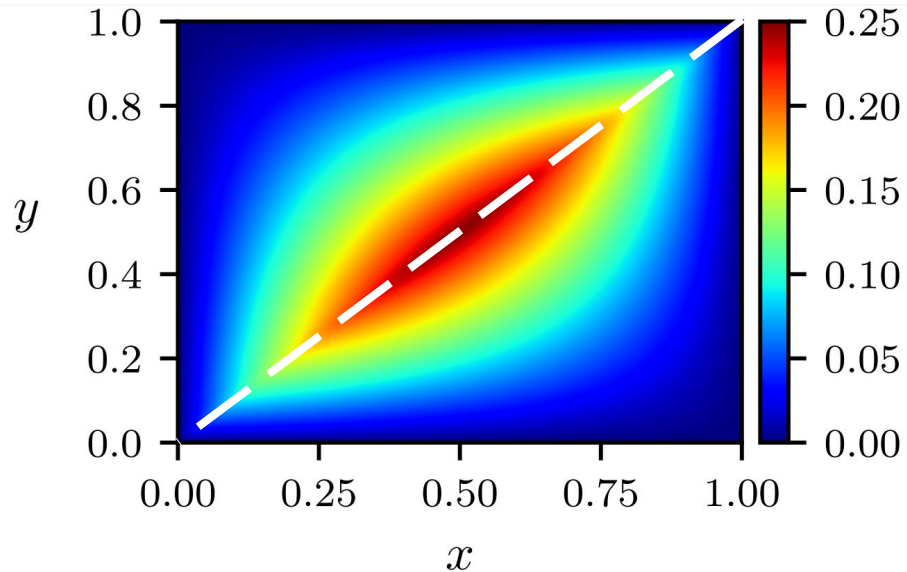
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Randomized SVD for Green's functions

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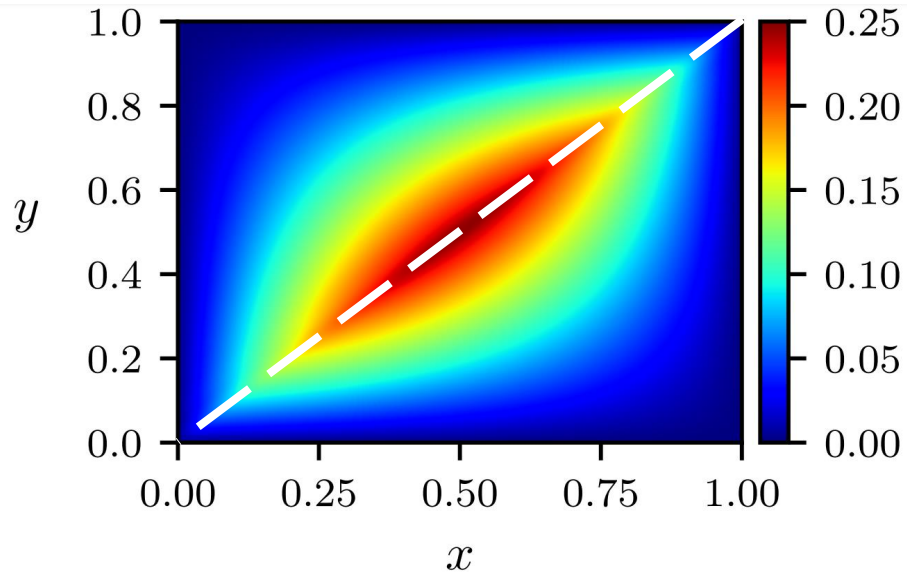
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Problem:

The Green's functions are not smooth near the diagonal.

Randomized SVD for Green's functions

Green's function



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$$\mathbb{P} \left[\|G - G_k\|_{L^2} \leq \mathcal{O} \left(\sqrt{k^2 / \gamma_k} \right) \epsilon_k \right] \geq 0.999$$

Problem:

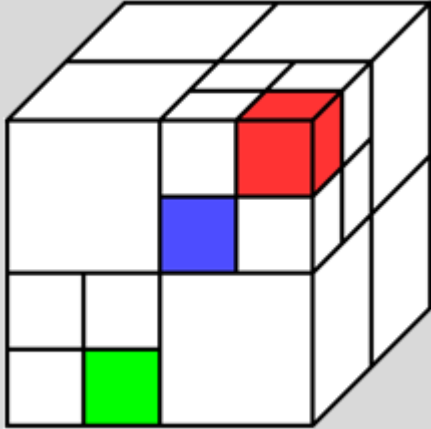
The Green's functions are not smooth near the diagonal.



ϵ_k decays very slowly with k

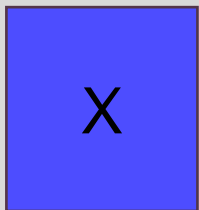
Regularity of the Green's function

Low-rank structure

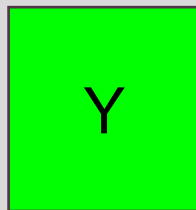


Low-rank structure on well separated domains.

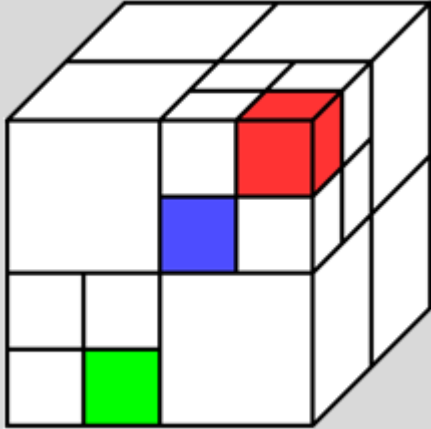
[Bebendorf, Hackbush, 2003]



\times

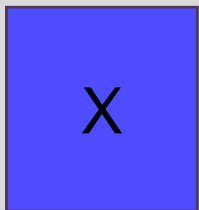


Low-rank structure

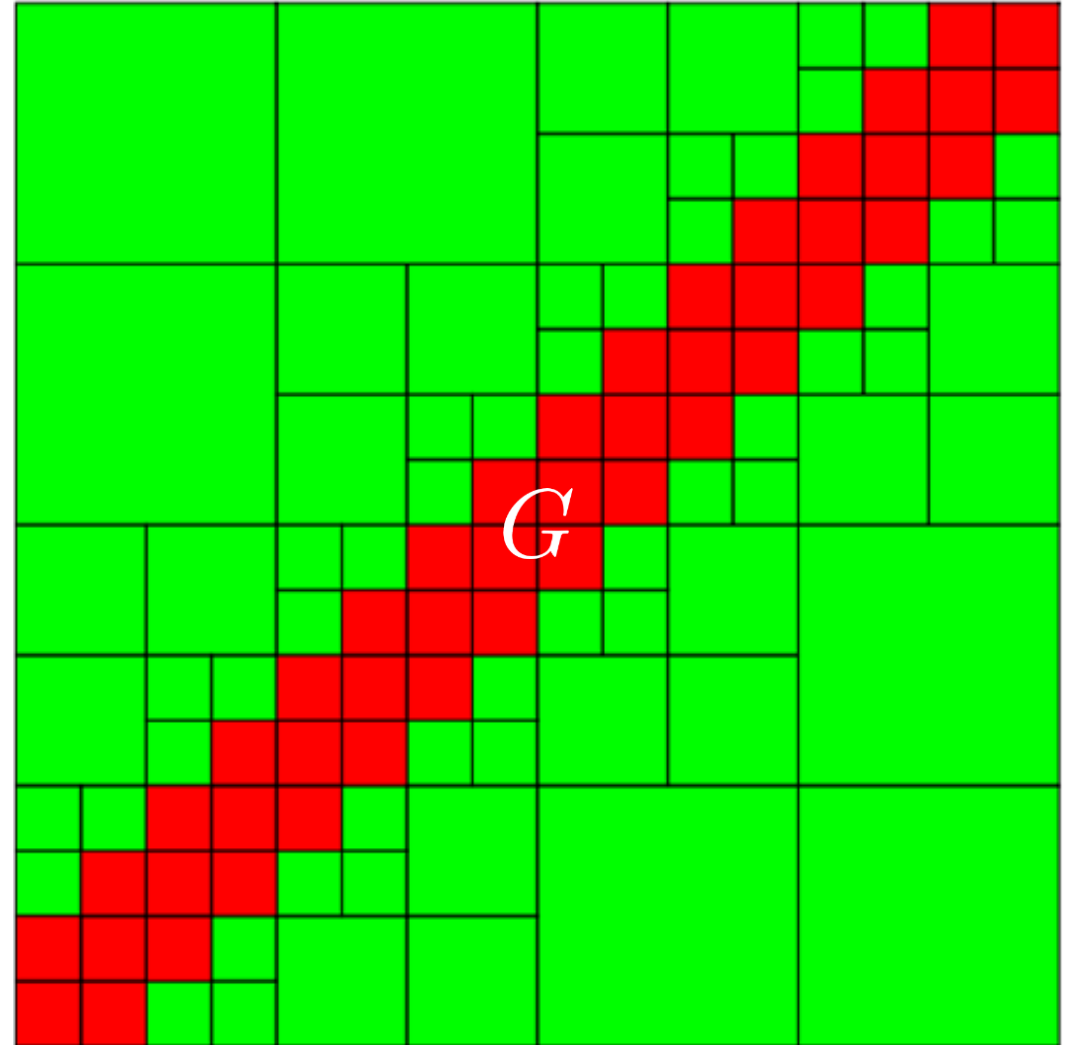
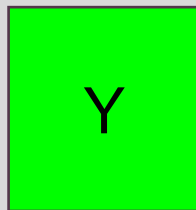


Low-rank structure on well separated domains.

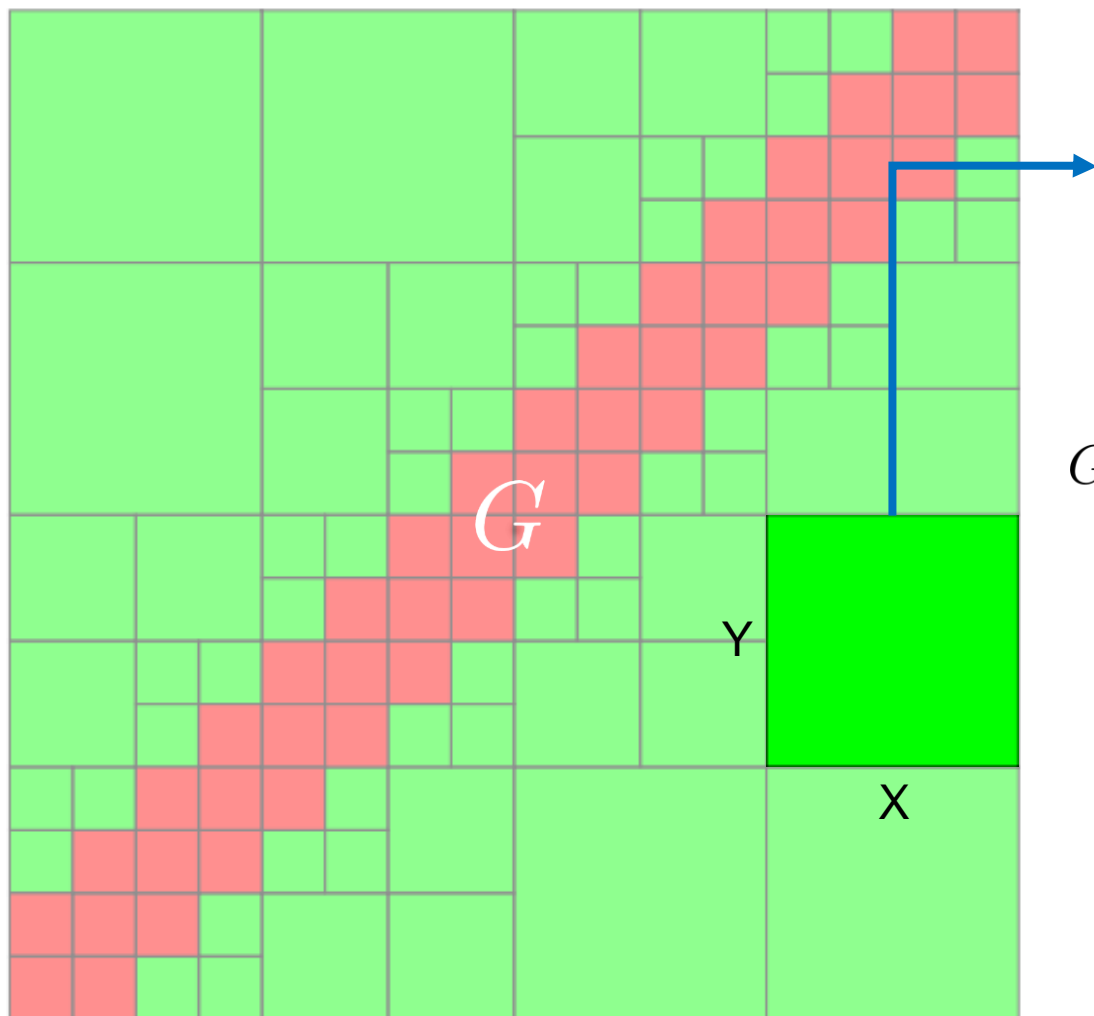
[Bebendorf, Hackbush, 2003]



\times

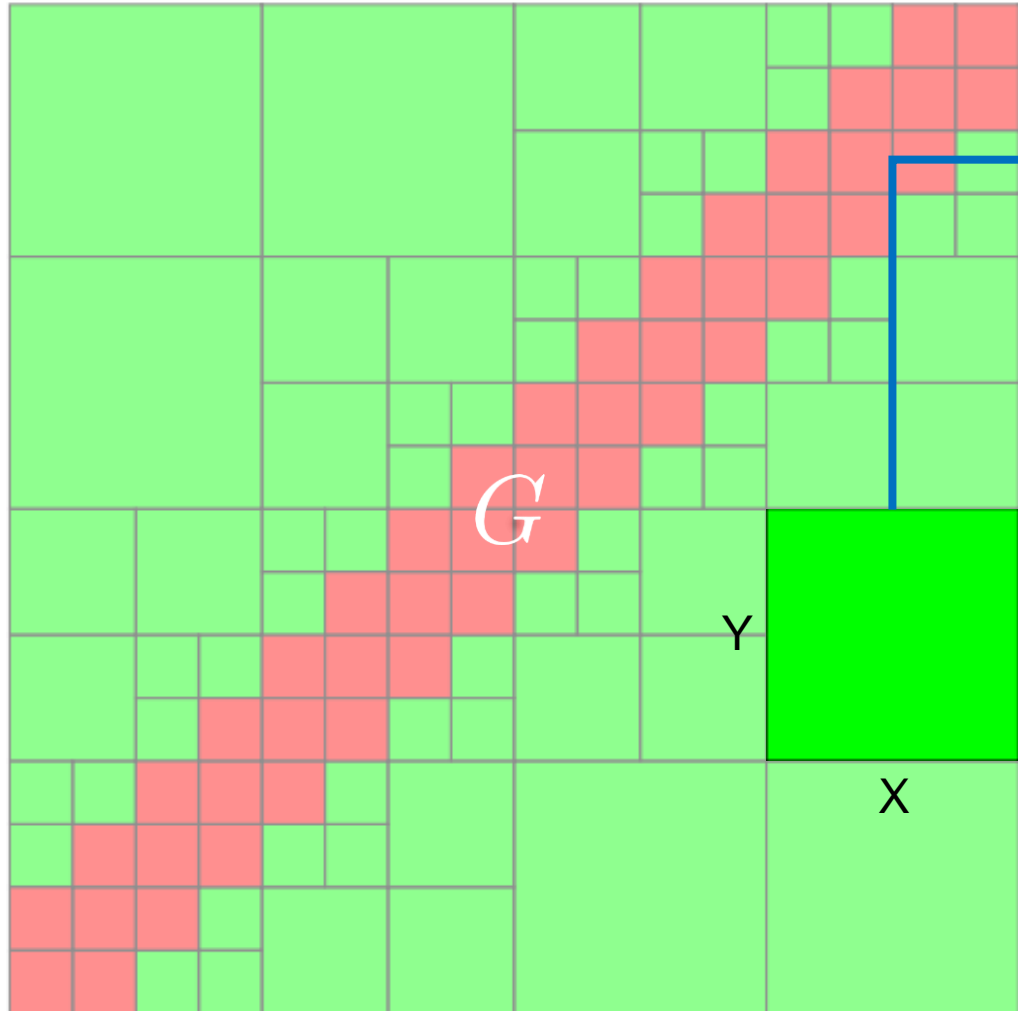


Hierarchical reconstruction

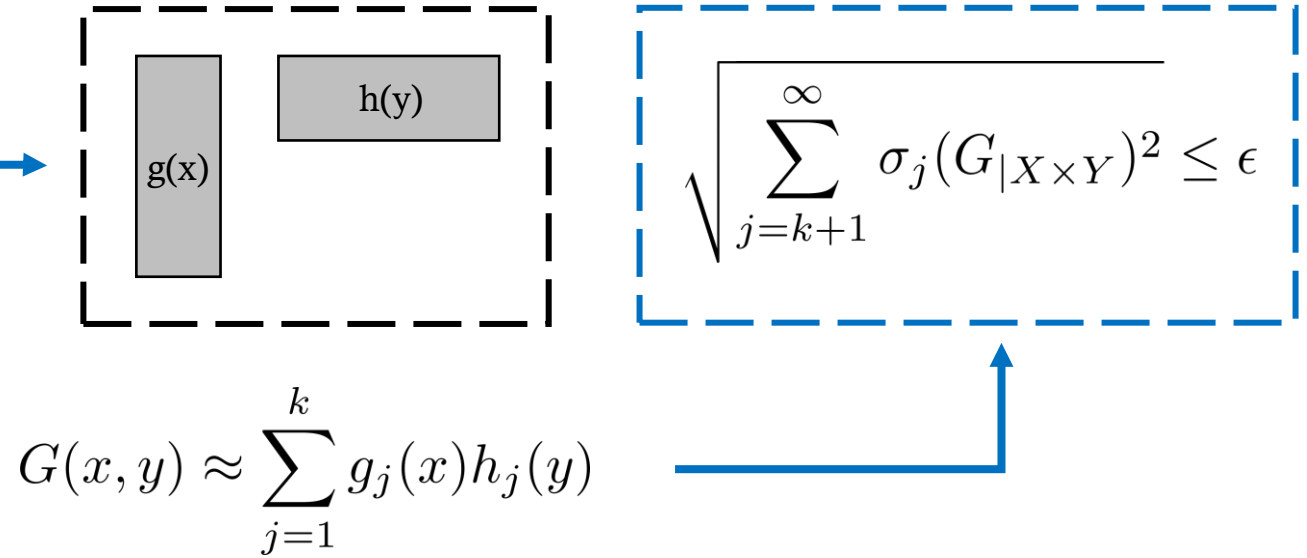


$$G(x, y) \approx \sum_{j=1}^k g_j(x) h_j(y)$$

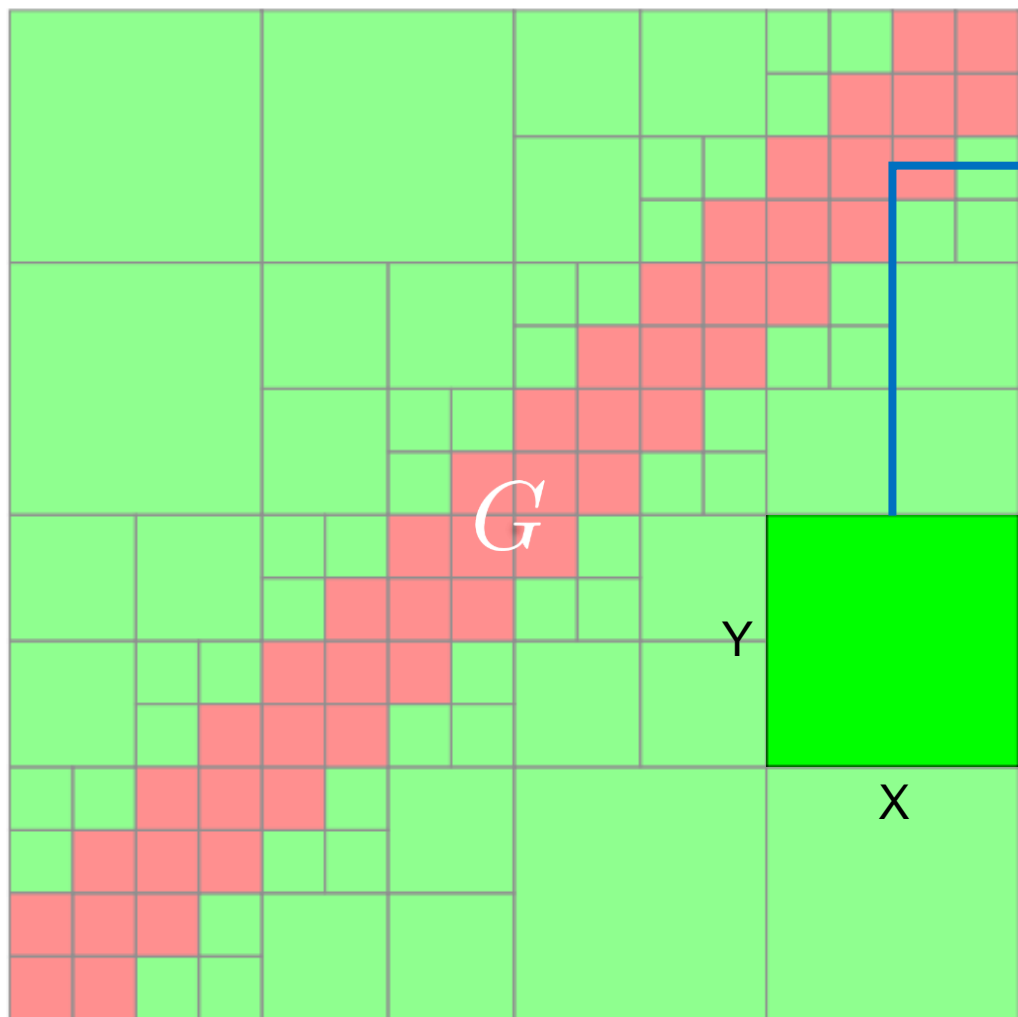
Hierarchical reconstruction



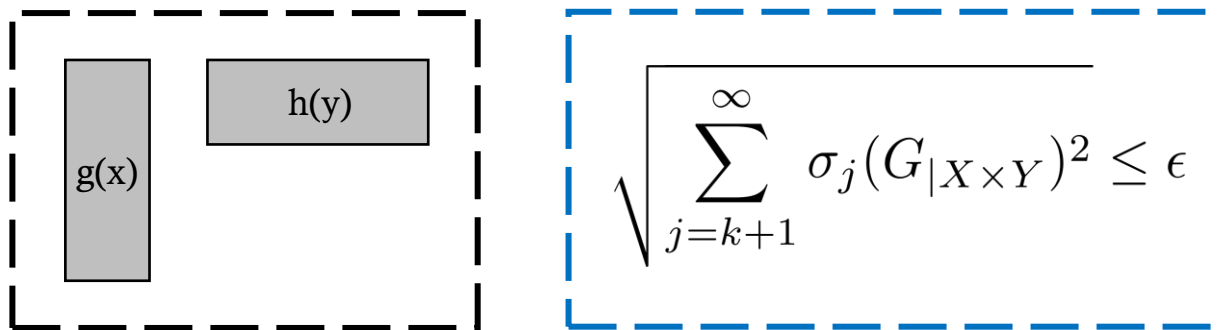
Randomized SVD on each subdomain



Hierarchical reconstruction



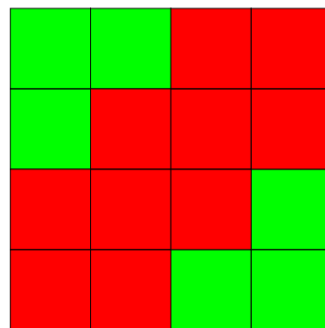
Randomized SVD on each subdomain



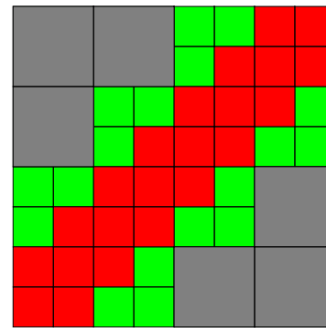
$$G(x, y) \approx \sum_{j=1}^k g_j(x) h_j(y)$$

Hierarchical structure

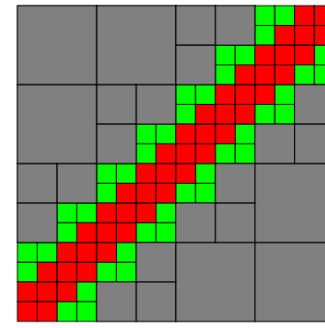
Level 2



Level 3



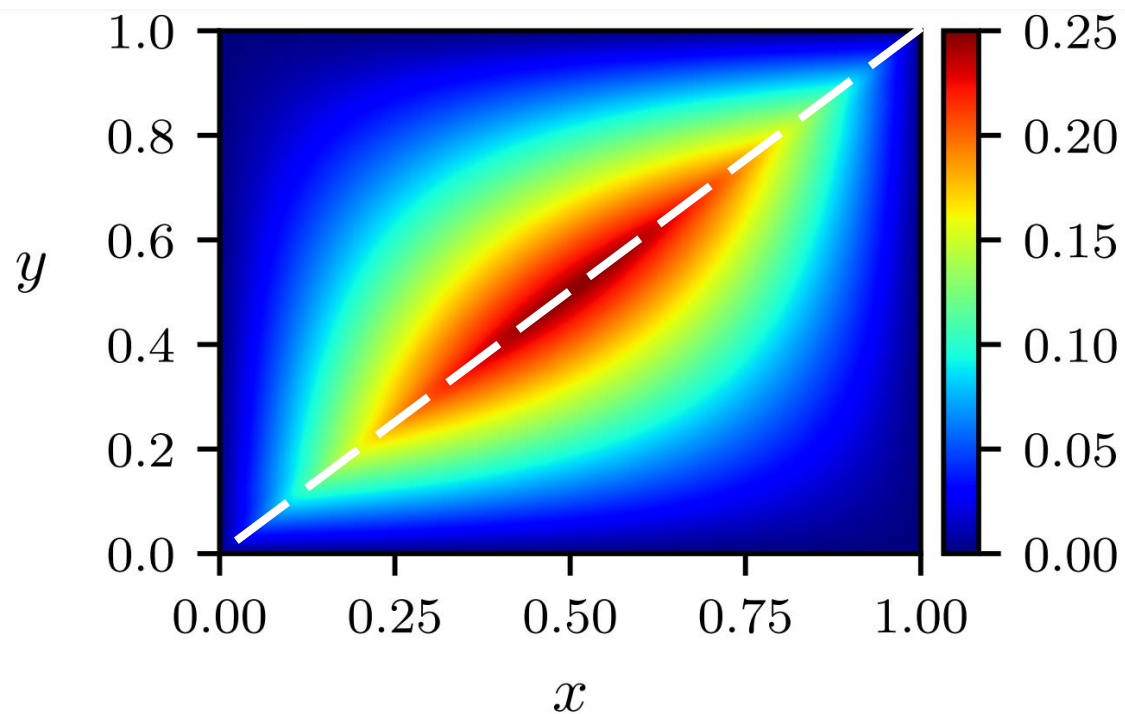
Level 4



Off-diagonal decay

Green's function of the Laplace operator:

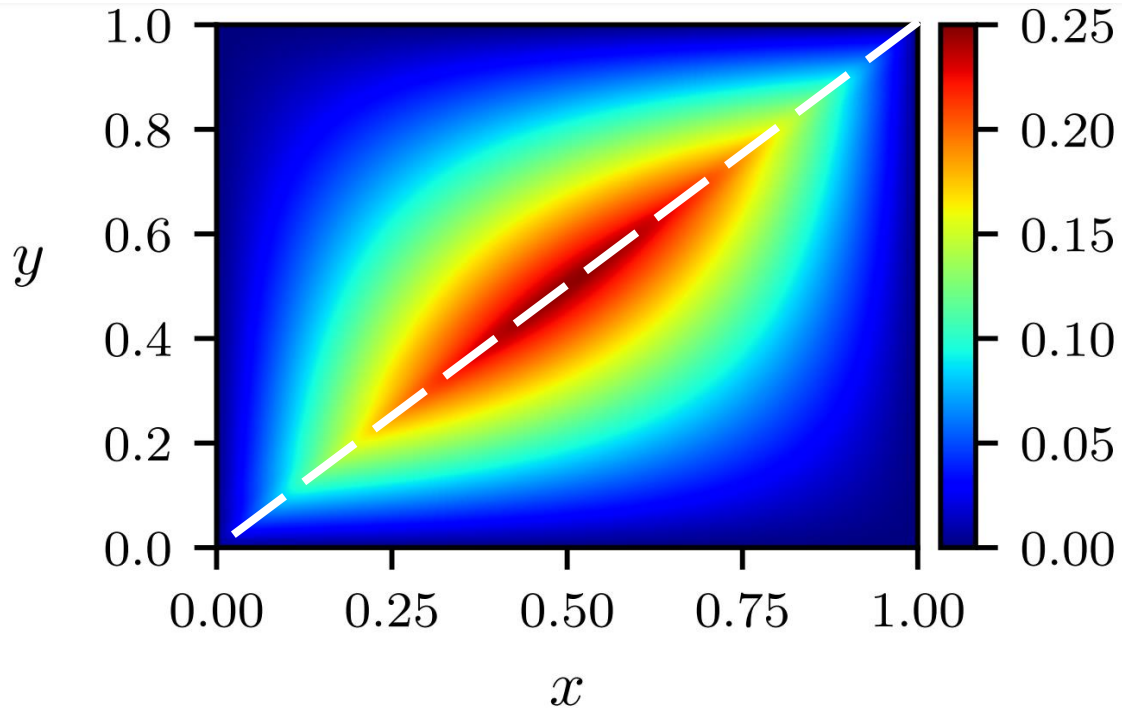
$$-\nabla^2 u = f$$



Off-diagonal decay

Green's function of the Laplace operator:

$$-\nabla^2 u = f$$



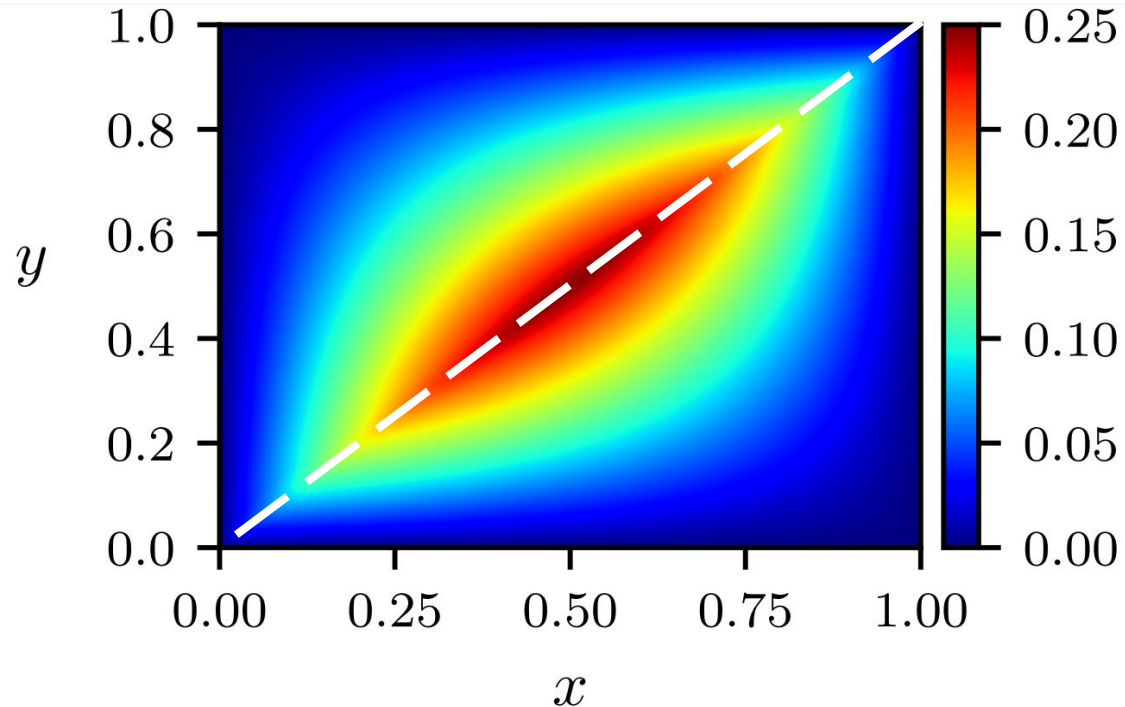
Green's functions are smooth and decay off the diagonal. [Grüter, Widman, 1982]

$$G(x, y) \leq \frac{1}{\|x - y\|}$$

Off-diagonal decay

Green's function of the Laplace operator:

$$-\nabla^2 u = f$$

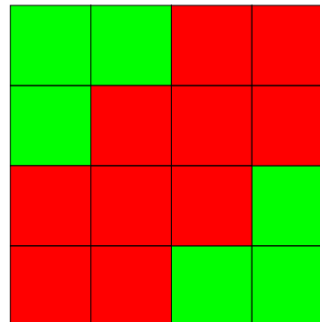


Green's functions are smooth and decay off the diagonal. [Grüter, Widman, 1982]

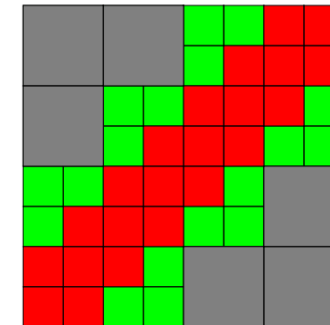
$$G(x, y) \leq \frac{1}{\|x - y\|}$$

Hierarchical structure

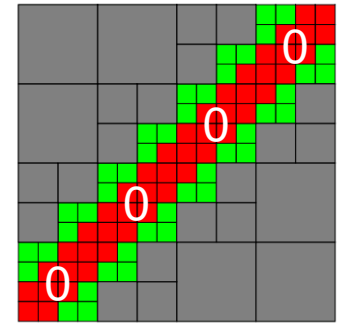
Level 2



Level 3



Level 4



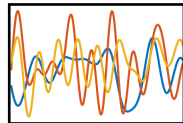
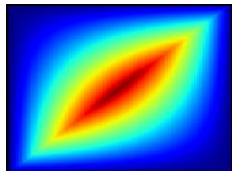
Summary of the result

Theorem (B., Halikias, Townsend, 2023).

*There is a randomized algorithm that achieves **exponential convergence** for learning the Green's function, with exceptionally high probability of success.*

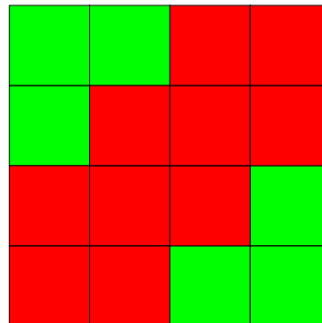
Randomized SVD

$$\int_D G(x, y) f(y) dy$$

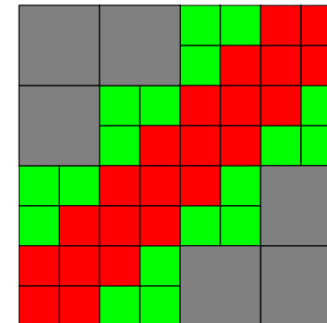


Hierarchical structure

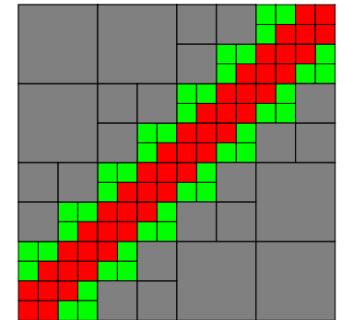
Level 2



Level 3



Level 4



Summary of the result

Theorem (B., Halikias, Townsend, 2023).

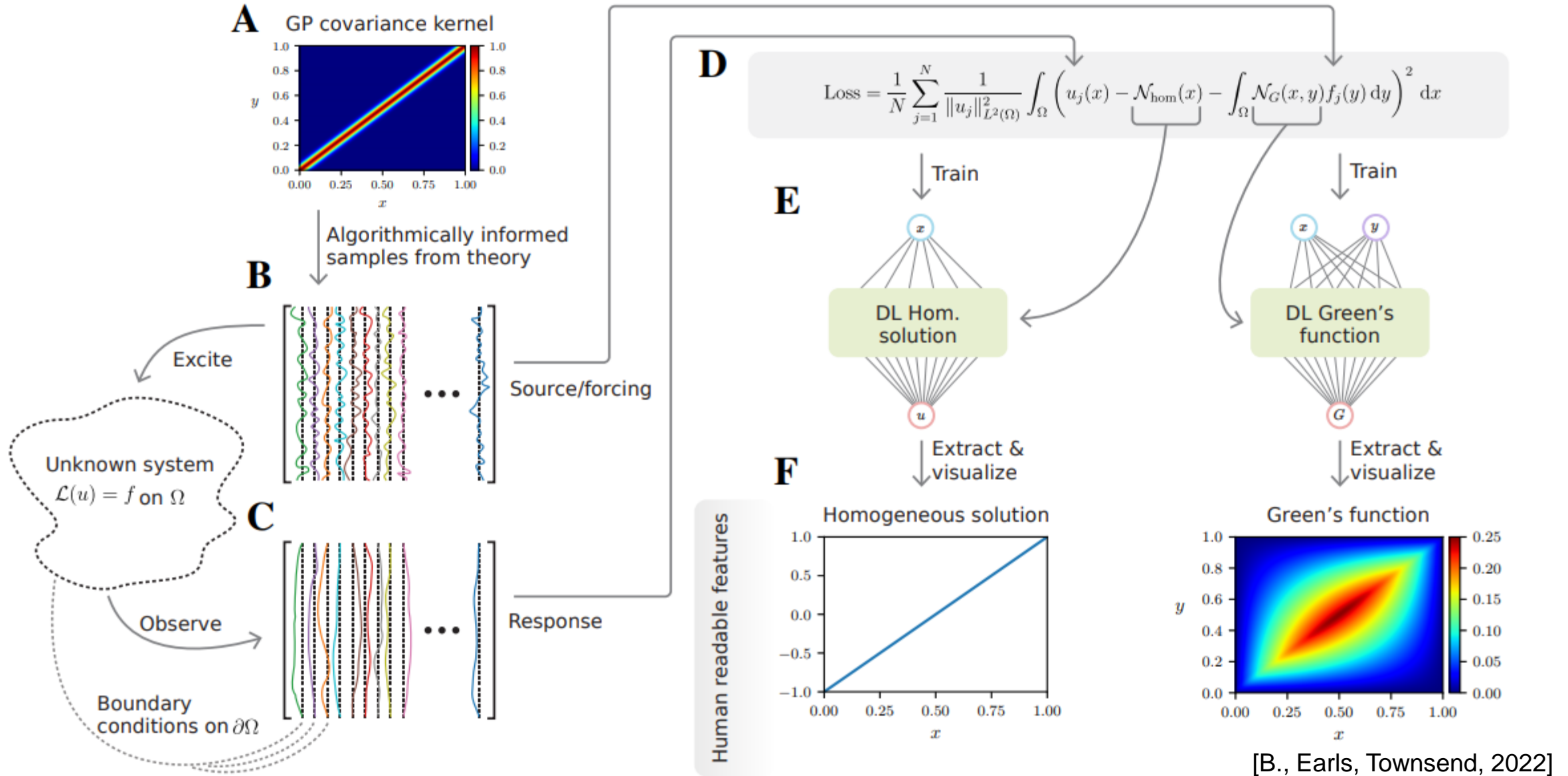
*There is a randomized algorithm that achieves **exponential convergence** for learning the Green's function, with exceptionally high probability of success.*

Extension to time-dependent PDEs of the form:

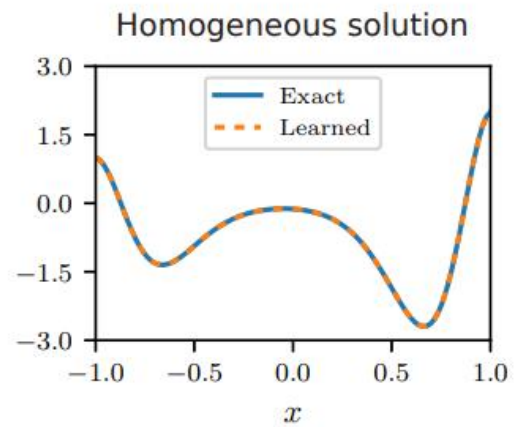
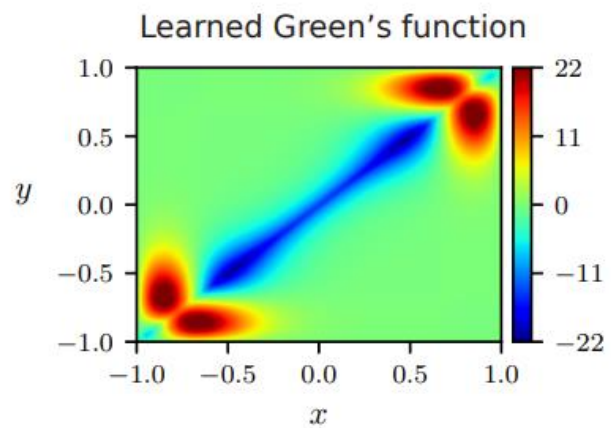
$$u_t - \nabla \cdot (A(x, t) \nabla u) = f(x, t)$$

Deep learning applications

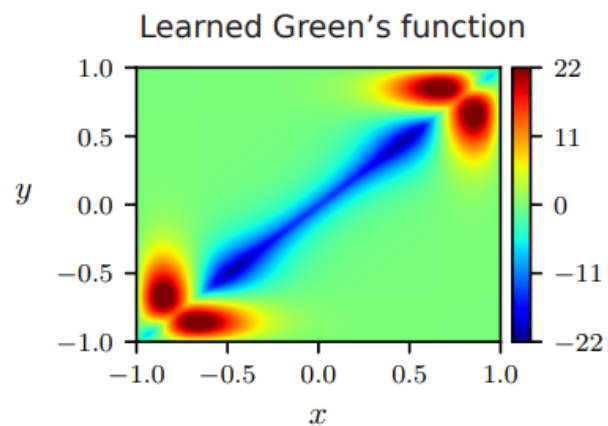
Deep learning method



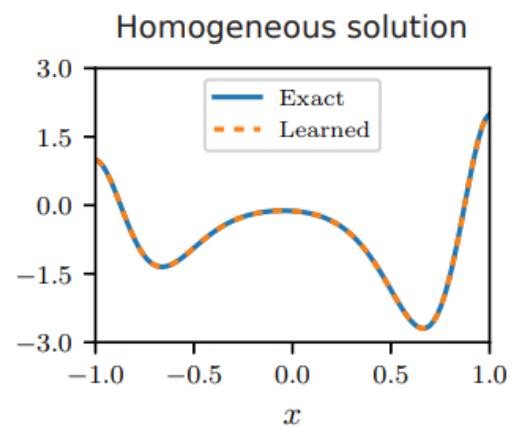
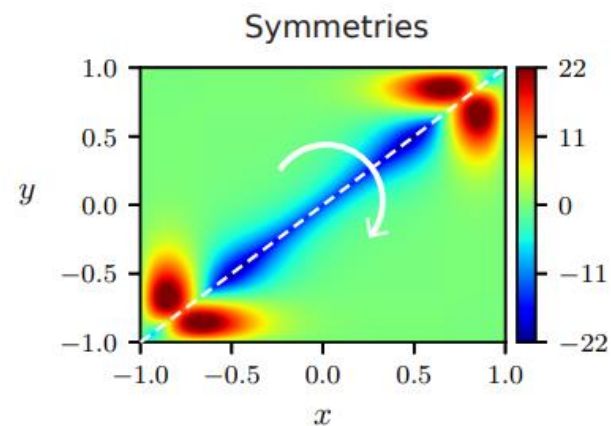
Learning features of the PDE



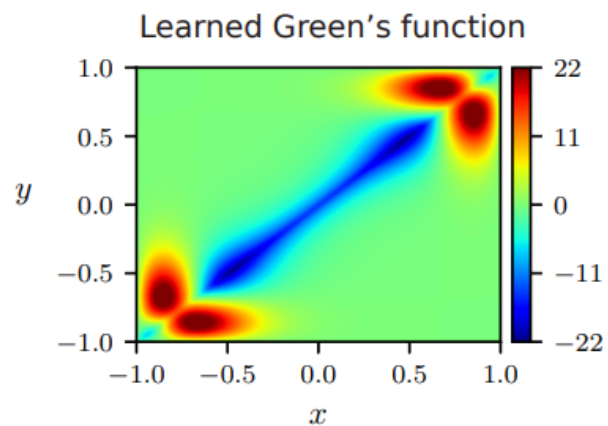
Learning features of the PDE



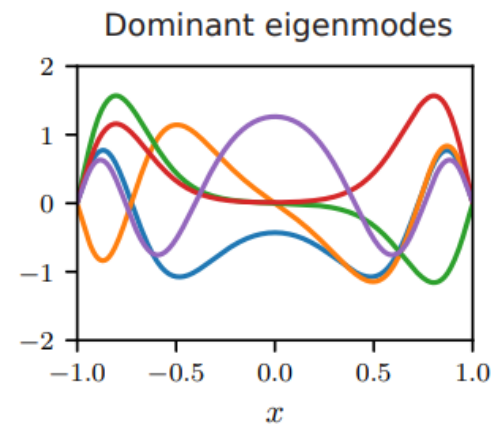
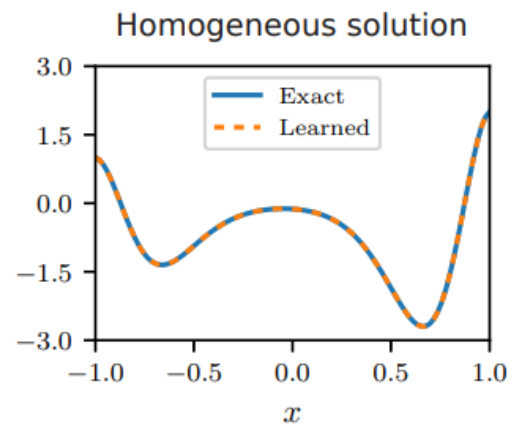
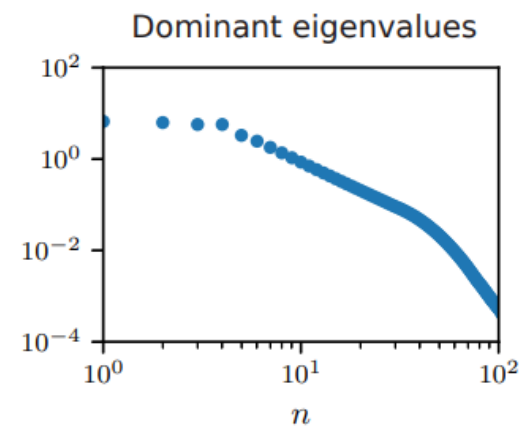
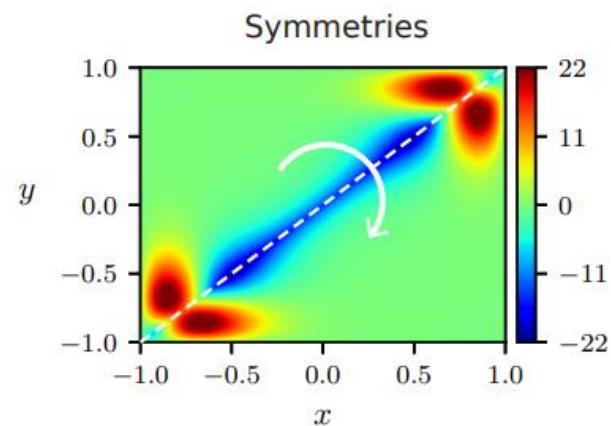
Extract features



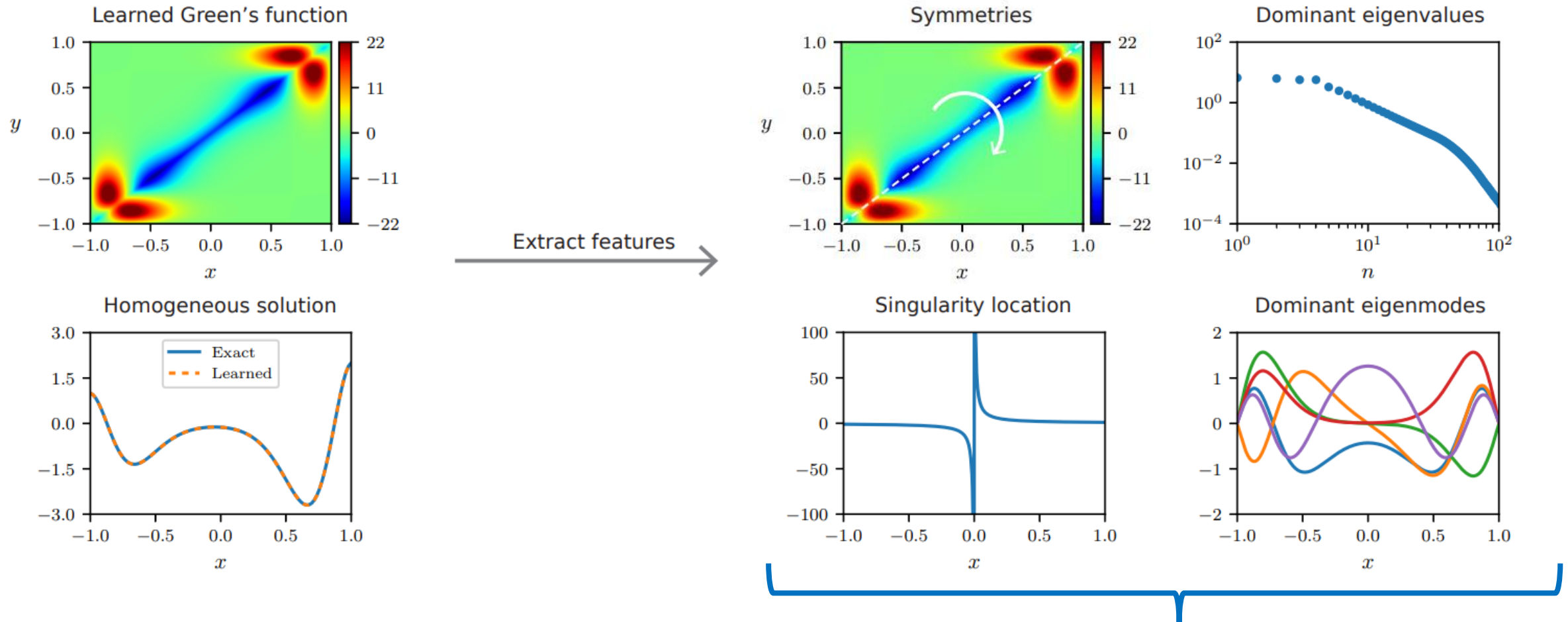
Learning features of the PDE



Extract features



Learning features of the PDE



Rational neural networks have high approximation power and support feature extraction [B., Nakatsukasa, Townsend, 2020]

Advection-diffusion equation

Equation:

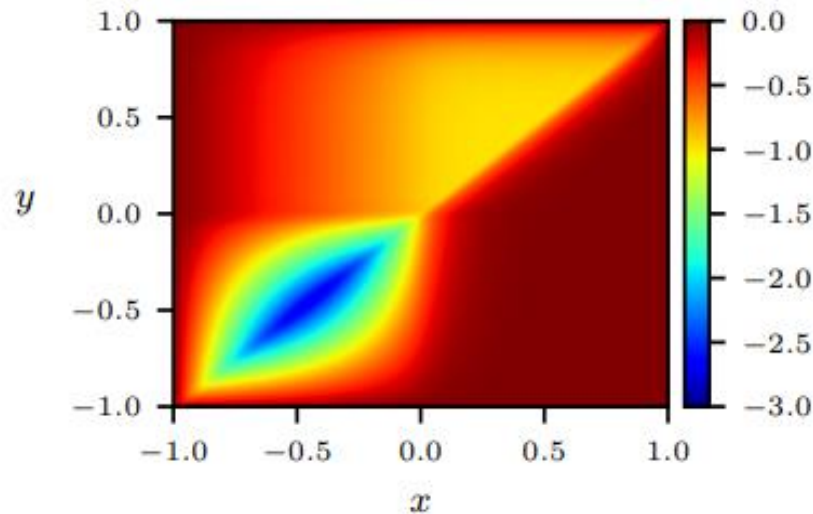
$$\mathcal{L}u = 0.1 \frac{d^2 u}{dx^2} + (x \geq 0) \frac{du}{dx}, \quad u(-1) = 2, \quad u(1) = -1$$

Advection-diffusion equation

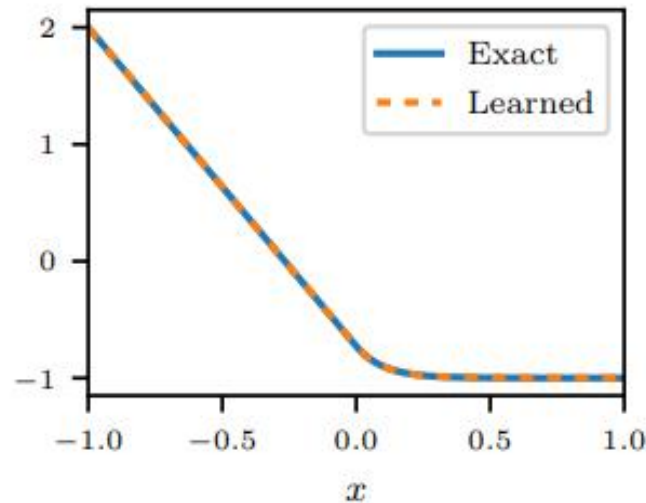
Equation:

$$\mathcal{L}u = 0.1 \frac{d^2 u}{dx^2} + (x \geq 0) \frac{du}{dx}, \quad u(-1) = 2, \quad u(1) = -1$$

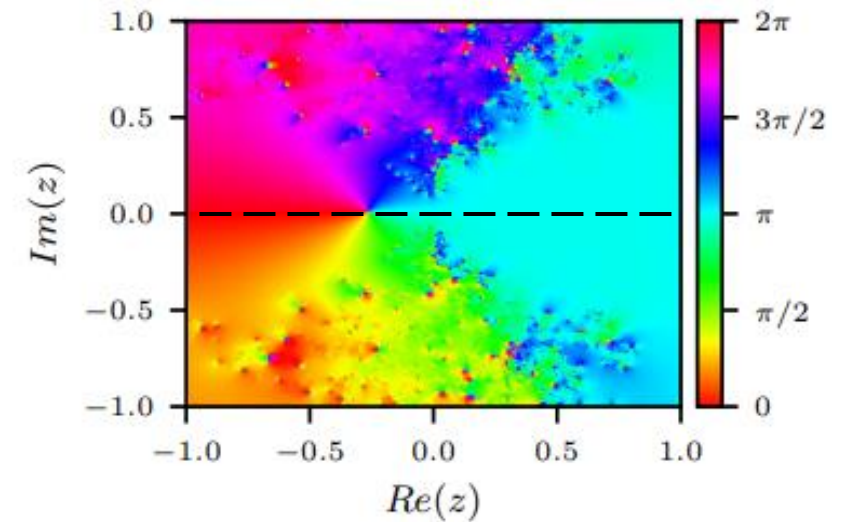
Green's function



Homogeneous solution

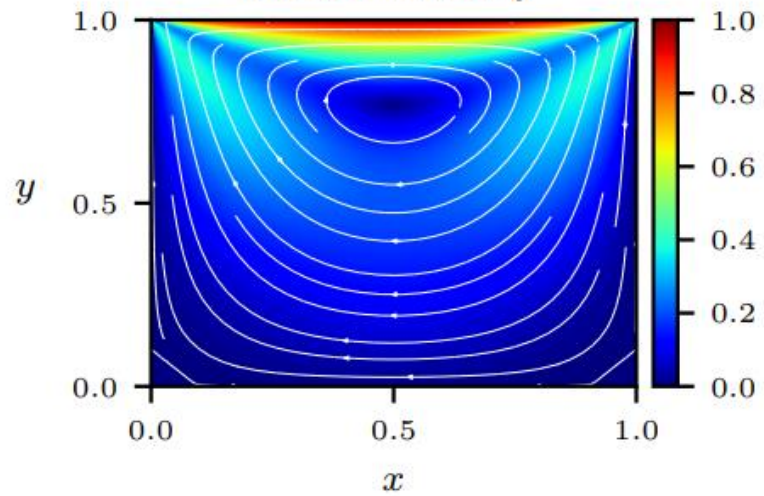


Phase portrait

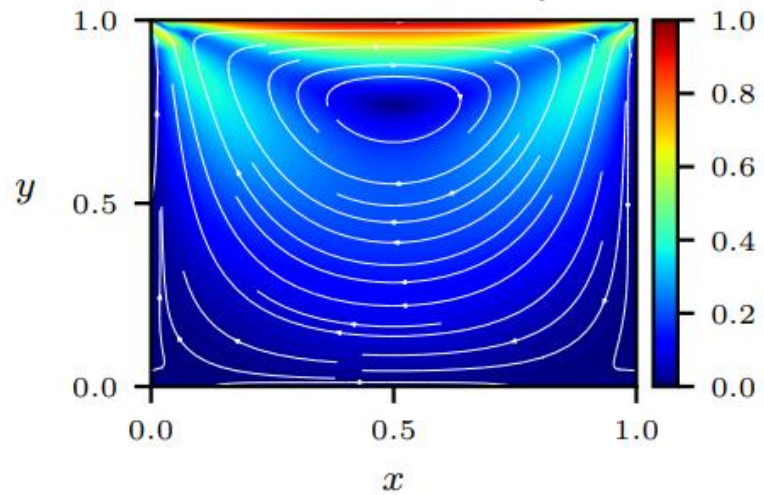


Stokes flow in a lid-driven cavity

Exact velocity

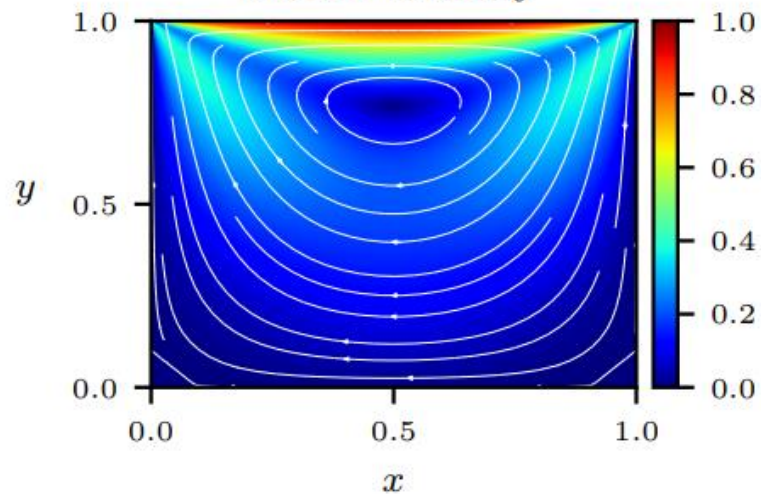


Learned velocity

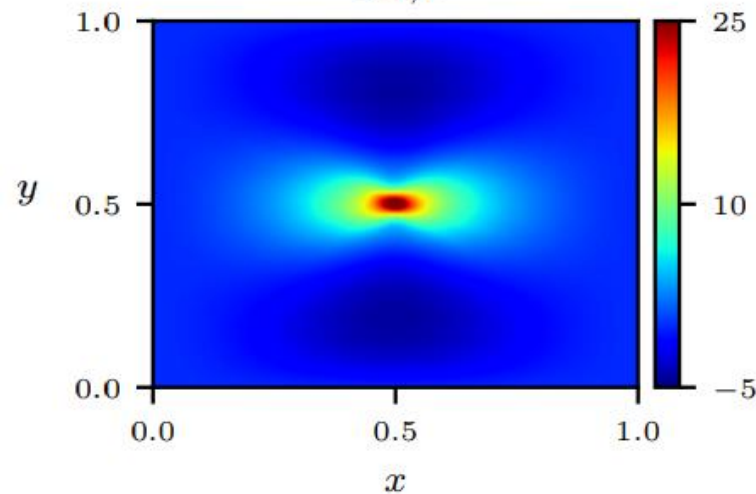


Stokes flow in a lid-driven cavity

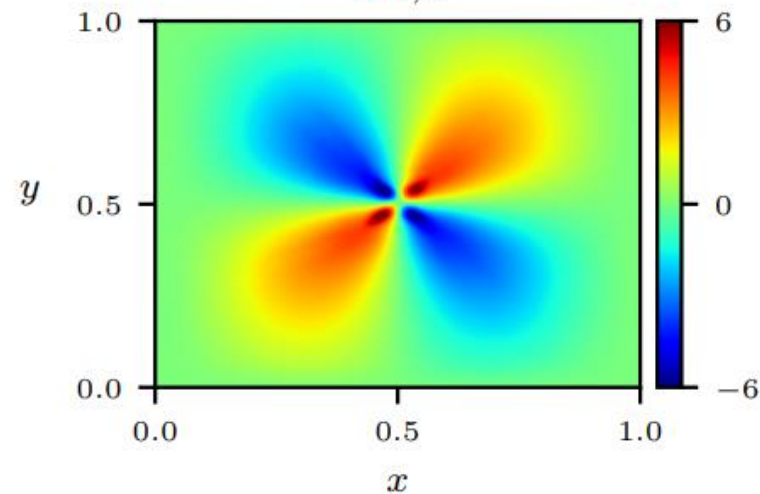
Exact velocity



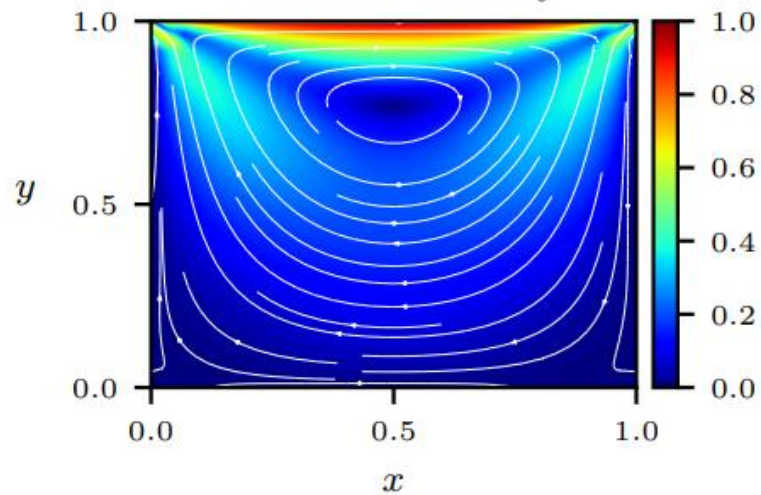
$G_{1,1}$



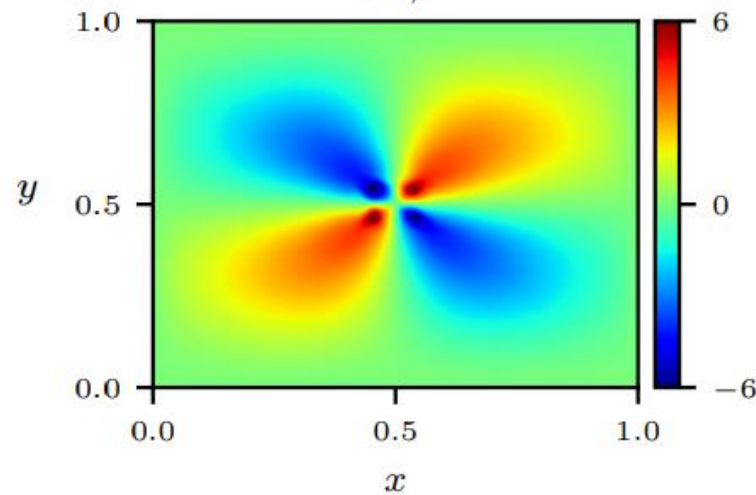
$G_{1,2}$



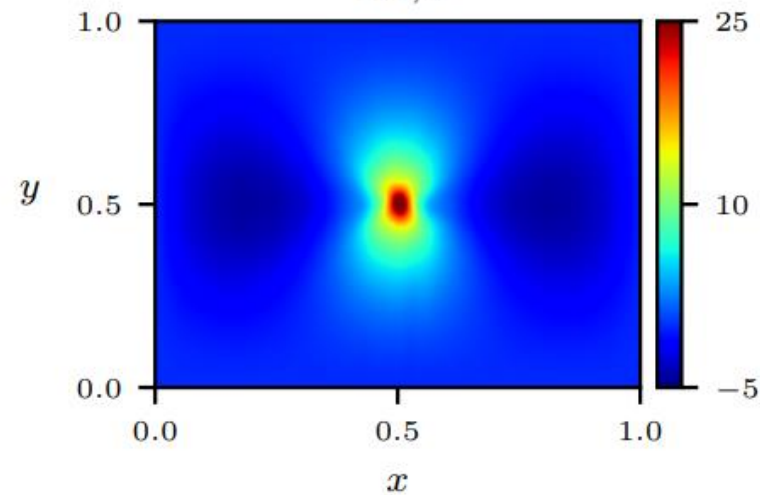
Learned velocity



$G_{2,1}$



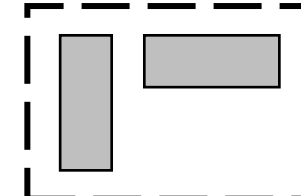
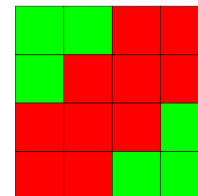
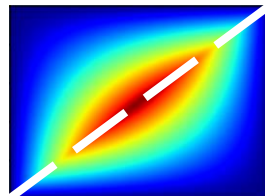
$G_{2,2}$



Conclusions

1. Theory for learning Green's functions

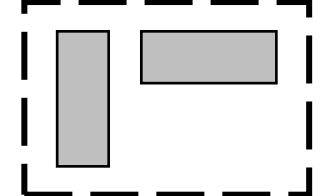
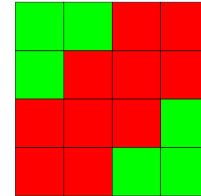
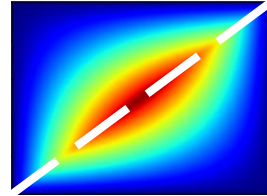
$$\mathcal{L}u = -\nabla \cdot (A(x)\nabla u)$$



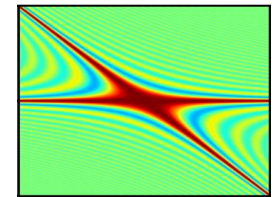
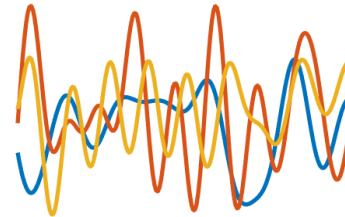
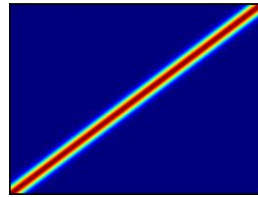
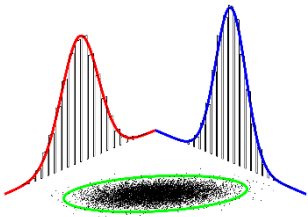
Conclusions

1. Theory for learning Green's functions

$$\mathcal{L}u = -\nabla \cdot (A(x)\nabla u)$$



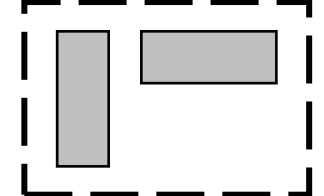
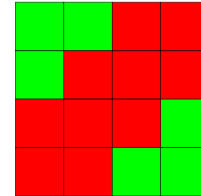
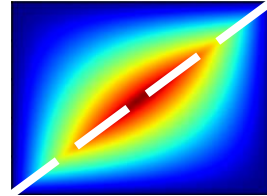
2. Generalization of the randomized SVD



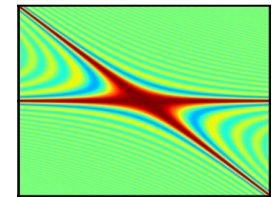
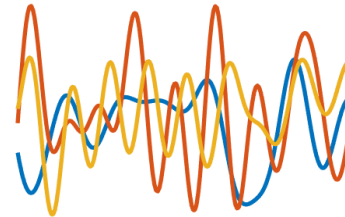
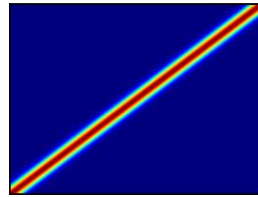
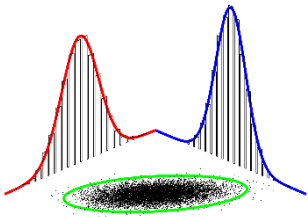
Conclusions

1. Theory for learning Green's functions

$$\mathcal{L}u = -\nabla \cdot (A(x)\nabla u)$$



2. Generalization of the randomized SVD



3. Deep learning approach



Python package

```
pip install greenlearning
```

